



Evolution Operators and Boundary Conditions for Propagation and Reflection Methods

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Outline

- Fundamental Equations
- Non-Local Boundary Conditions
- Improving Accuracy in Fast Reflection Calculations



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Part I - Fundamental Equations



Scalar Wave Equation

- Scalar, Monochromatic Electric Field

$$\left(\frac{\partial^2}{\partial z^2} + \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + k_0^2 n^2(\vec{r}) \right) \mathbf{E}(x, y, z) = 0$$

Defining $n_0 = n_{reference}$, $X_0 = \frac{1}{k_0^2 n_0^2} \frac{\partial^2}{\partial x^2}$,

$Y_0 = \frac{1}{k_0^2 n_0^2} \frac{\partial^2}{\partial y^2}$ and $N = \frac{n^2(\vec{r})}{n_0^2} - 1$, we have

$$\left(\frac{\partial^2}{\partial z^2} + k_0^2 n_0^2 (X_0 + Y_0 + N) \right) \mathbf{E}(x, y, z) = 0$$



Forward Solution

- Define $H = X_0 + Y_0 + N$. For forward-travelling waves ($e^{i\omega t}$ time-dependence)

$$\left(\frac{\partial}{\partial z} + ik_0 n_0 \sqrt{1 + H} \right) \mathbf{E}(x, y, z) = 0$$

- We then have with $\delta = -ik_0 n_0$

$$\mathbf{E}(x, y, z + \Delta z) = e^{\delta \Delta z \sqrt{1 + H}} \mathbf{E}(x, y, z)$$



Modal Analysis

- Modal Decomposition

$$\mathbf{E}(x, y, \bar{z}) = \sum_m a_m \mathbf{E}_m(x, y, \bar{z}) \quad \text{with}$$

$$\left[\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + k_0^2 n^2(x, y, \bar{z}) \right] \mathbf{E}_m(x, y, \bar{z}) = \beta_m^2(x, y, \bar{z}) \mathbf{E}_m(x, y, \bar{z})$$

- Approximate Forward Solution

$$\mathbf{E}(x, y, z + \Delta z) = \sum_m e^{-i\beta_m(x, y, \bar{z})\Delta z} \mathbf{E}_m(x, y, z)$$



Fresnel Approximation

- Fresnel Approximation

$$\sqrt{1 + H} \approx 1 + \frac{H}{2}$$

- Slowly-Varying Envelope $E(x, y, z) = \mathbf{E}(x, y, z)e^{-\delta z}$

$$\left(\frac{\partial}{\partial z} + \frac{\delta}{2} (X_0 + Y_0 + N) \right) E(x, y, z) = 0$$



Wide-Angle Approximations

- Taylor Series Expansion

$$\sqrt{1+H} \approx 1 + \frac{1}{2}H - \frac{1}{8}H^2 + \frac{1}{16}H^3 - \frac{5}{128}H^4 + O(H^5)$$

- Padé [2,0] approximant:

$$\sqrt{1+H} \approx 1 + \frac{H}{2} - \frac{H^2}{8}$$

- Padé [1,1] approximant

$$\begin{aligned}\sqrt{1+H} &\approx \frac{1+3H/4}{1+H/4} \\ &= 1 + \frac{1}{2}H - \frac{1}{8}H^2 + \frac{1}{32}H^3 - \frac{1}{128}H^4 + O(H^5)\end{aligned}$$



Square-Root Operator Recursion

- Recursion Relation

$$\begin{aligned}\sqrt{1+H} - 1 &= (\sqrt{1+H} - 1) \left(\frac{\sqrt{1+H} + 1}{\sqrt{1+H} + 1} \right) \\ &= \frac{H}{\sqrt{1+H} + 1} \\ &= \frac{H}{2 + (\sqrt{1+H} - 1)}\end{aligned}$$

- Thus if $f(x) = \sqrt{1+H} - 1$ we have

$$f(x) = x / (2 + f(x))$$



Continued Fraction Expansion

- Iterating the recursion relation yields

$$\sqrt{1 + H} - 1 = \frac{H}{2 + \frac{H}{2 + \dots \frac{H}{2 + \frac{H}{2}}}}$$

- Note that we have employed $f(x) = 0$ to terminate the fraction, yielding a real expression.



Padé Representations

- The Padé approximant can be factored as

$$\sqrt{1+H} \approx \prod_{r=1}^s \left[\frac{1 + \sin^2\left(\frac{r\pi}{2s+1}\right)H}{1 + \cos^2\left(\frac{r\pi}{2s+1}\right)H} \right]$$

- In a partial fraction representation

$$\sqrt{1+H} = 1 + \sum_{r=1}^s \left[\frac{\frac{2}{2s+1} \sin^2\left(\frac{r\pi}{2s+1}\right)H}{1 + \cos^2\left(\frac{r\pi}{2s+1}\right)H} \right]$$



Finite Difference Method

- Applying a [1,1] Padé approximant yields the Crank-Nicholson procedure

$$\begin{aligned} E(z + \Delta z) &= e^{\frac{\delta H}{2}} E(z) \\ &= e^{\frac{\delta}{2}(X_0 + Y_0 + N)} E(z) \\ &\approx \left(\frac{1 + \delta H / 4}{1 - \delta H / 4} \right) E(z) + O(\delta^3) \end{aligned}$$



Discrete Representation

- On a one-dimensional transverse grid $\{x_i\}$

$$E(x_i, z + \Delta z) = \frac{1 - \frac{i\Delta z}{4k_0 n_0} (k_0^2 (n^2(x_i) - n_0^2) + D_x^2)}{1 + \frac{i\Delta z}{4k_0 n_0} (k_0^2 (n^2(x_i) - n_0^2) + D_x^2)} E(x_i, z)$$

where

$$D_x^2 E_i = \frac{E_{i+1} - 2E_i + E_{i-1}}{\Delta z^2}$$

and for any operator O , $\frac{1}{O}$ represents O^{-1} .

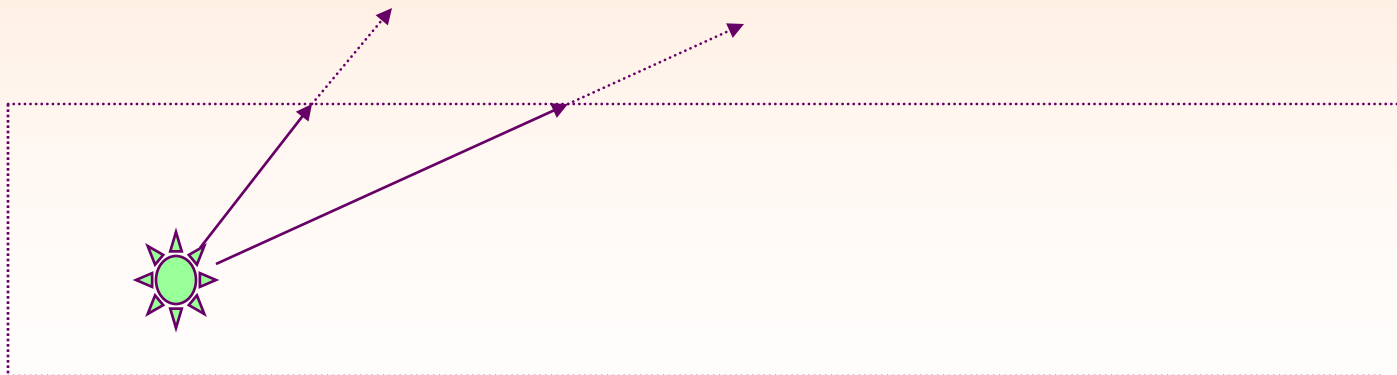


Part II - Nonlocal Boundary Conditions



Objective

- To simulate on a finite, discrete computational grid the field radiated from a local source into a homogeneous semi-infinite medium.

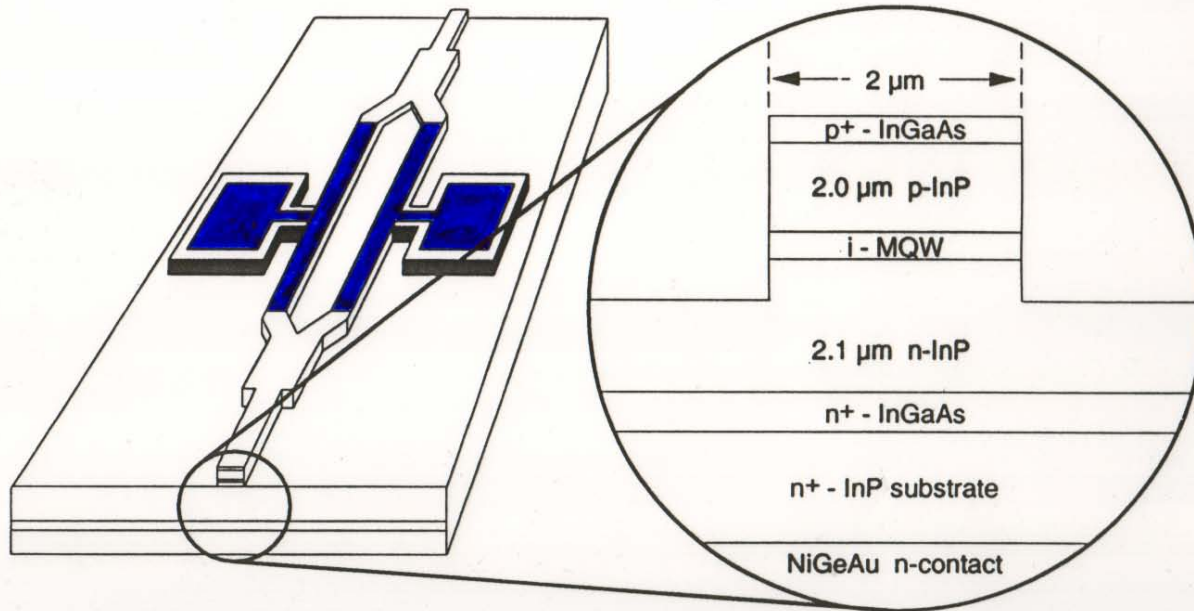




Electrorefraction Modulator

Schematic diagram of modulator

■ Ti / Pt / Au p-contact



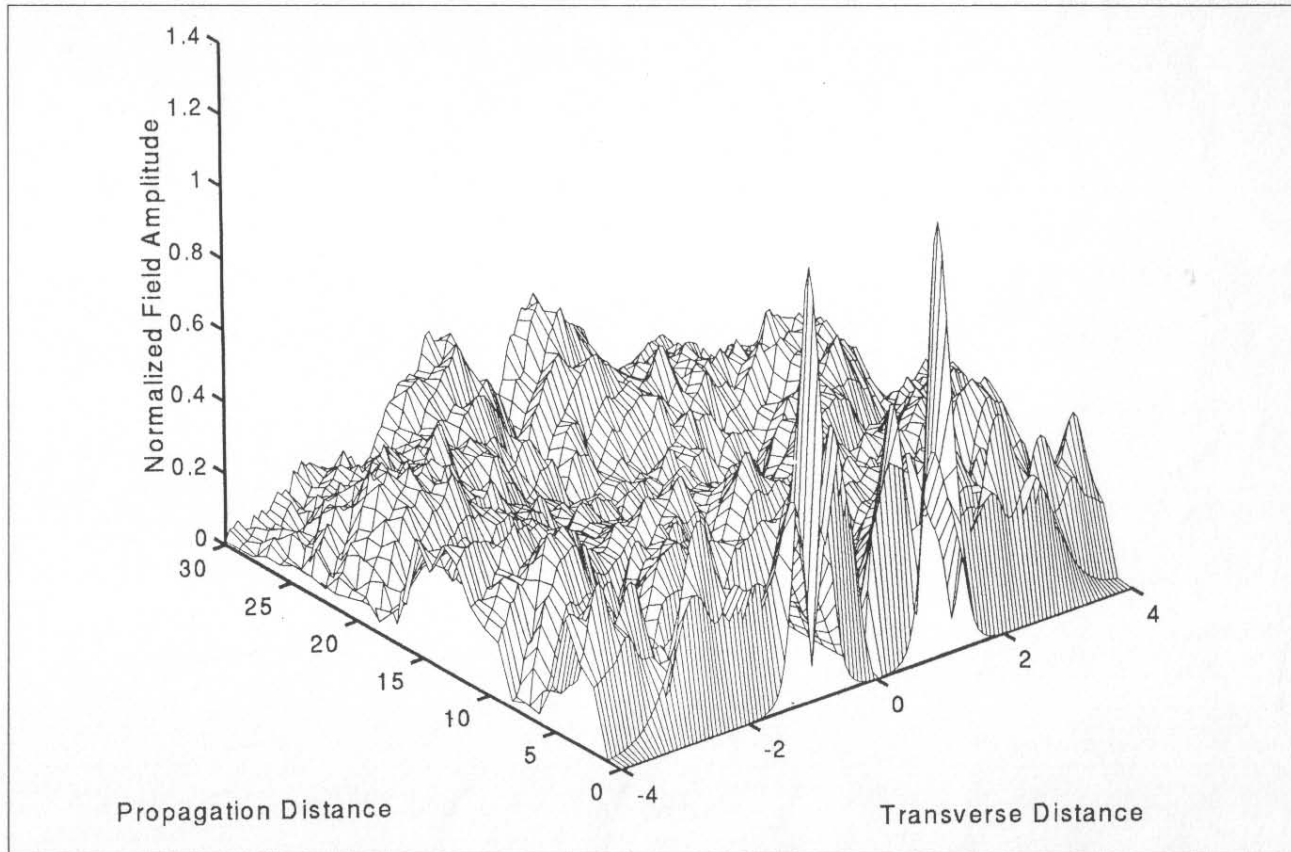


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Standard Boundary Conditions

Evolution of Unguided Asymmetric Field -
Standard Local Transparent Boundary

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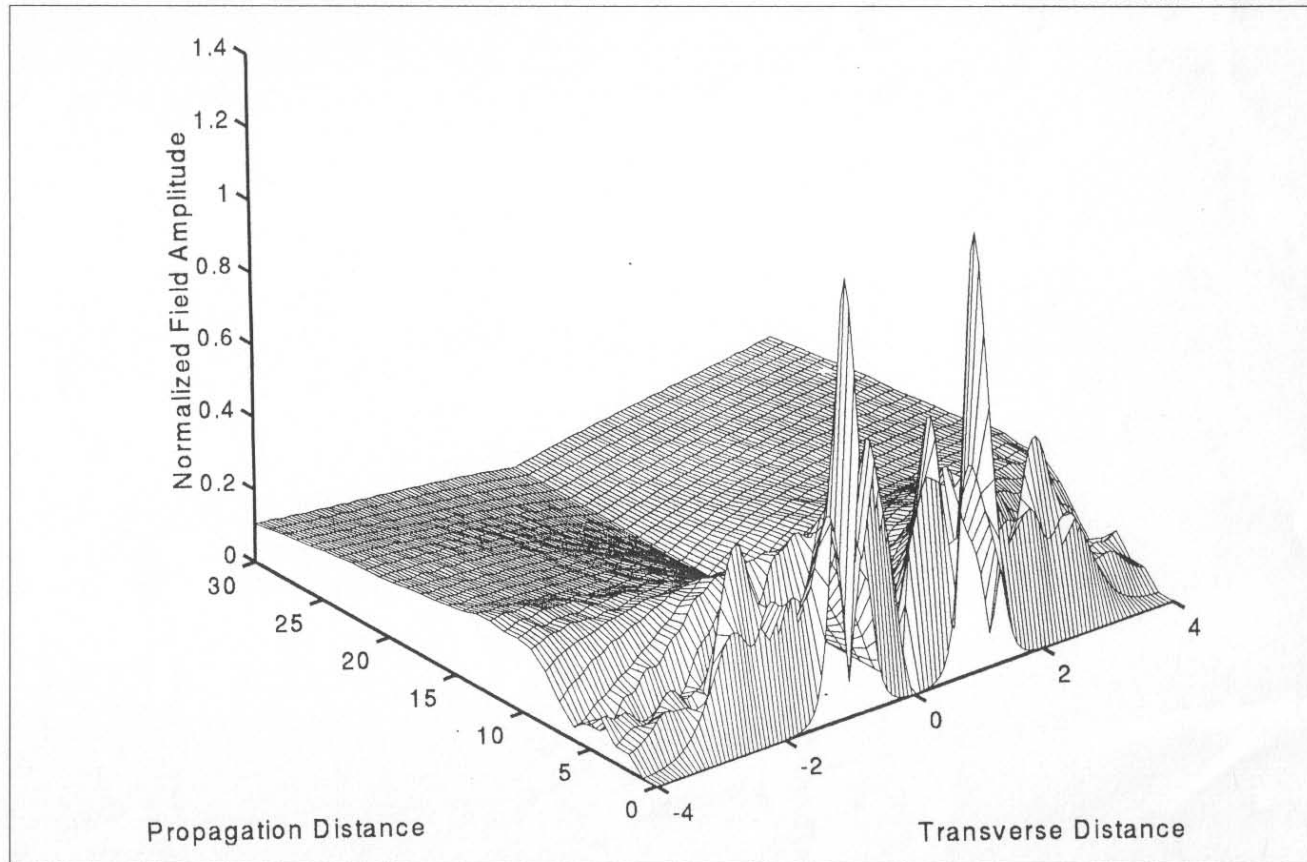




Improved Boundary Conditions

Evolution of Unguided Asymmetric Field -
Hybrid Boundary

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Boundary Layers

- The approximate propagation operators introduced above are unitary. To remove the outward propagating electric field at the boundary we can introduce absorbing or impedance-matched boundary layers.





Transparent Boundaries

- Set E_0 and E_{N+1} to be consistent with purely outgoing waves at the boundary.
 - Local Boundary Conditions: E_0, E_{N+1} are computed from E at the last propagation step.
 - Nonlocal Boundary Conditions: E_0, E_{N+1} are obtained from previous values of Ξ .





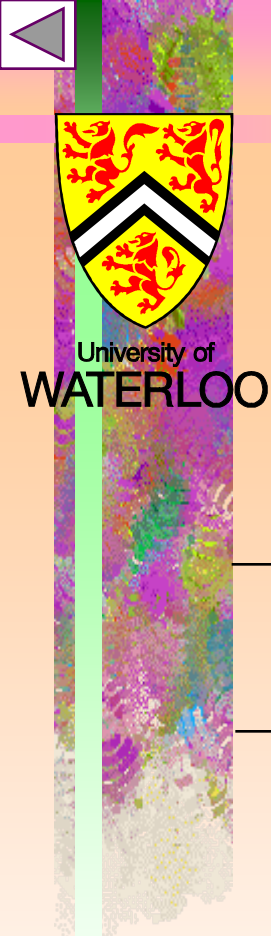
Impedance-Matched Layer

- For a non-equidistant grid, $\Delta X_i = (1 - b_i)\Delta X$ the governing equation in a homogeneous refractive index layer near the boundary is

$$\left(-2ik_0 n_0 \frac{\partial}{\partial z} + \frac{d^2}{dx^2} + k_0^2 (n_b^2 - n_0^2) \right) E(x, y, z) = 0$$

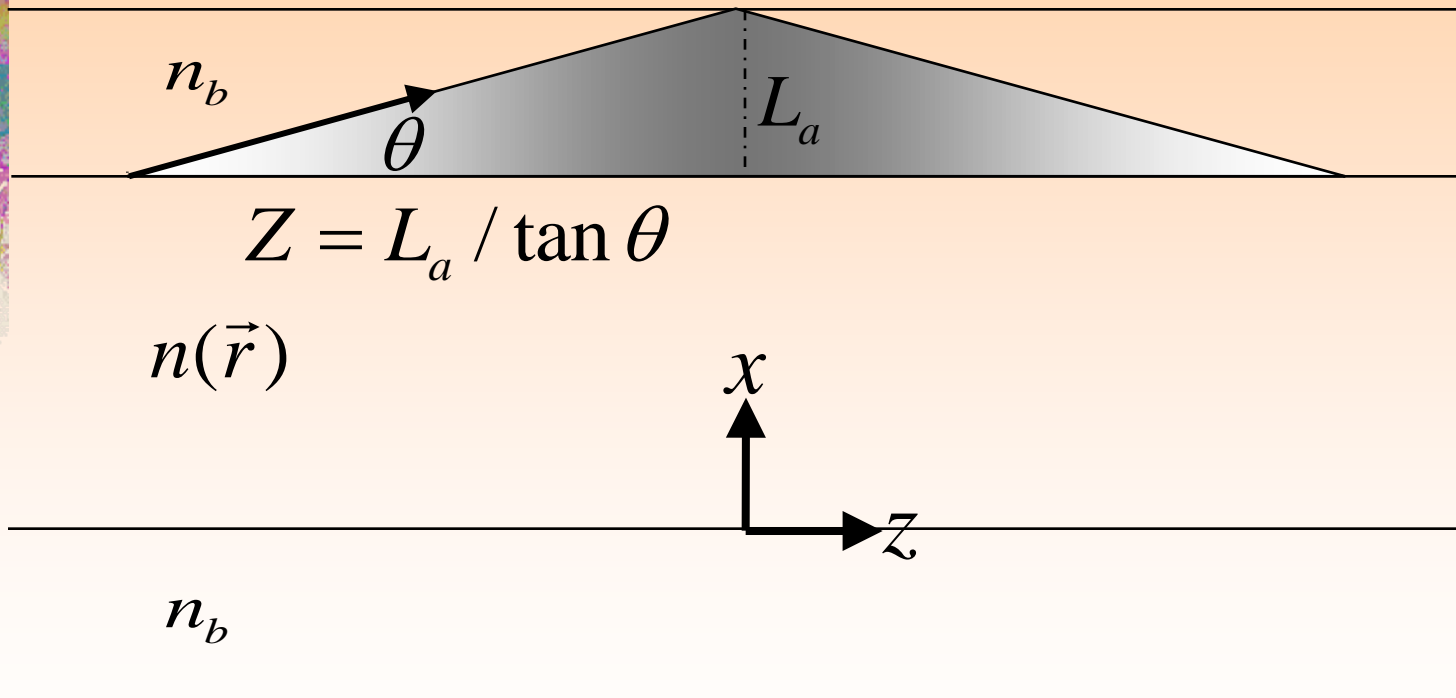
- For continuous x , z , no spurious effects.
- Thus, if $b_i \rightarrow ia_i$, we have

$$E_{k_x, k_z}(x, z) \propto e^{ik_x(1+ia_i)x + ik_z z}$$



Impedance-Matched Layer

$$\text{Attenuation} = e^{-2k_x \Delta x \sum_l a_l} = e^{-2k_0 n_b \Delta x \sin \theta \sum_l a_l}$$



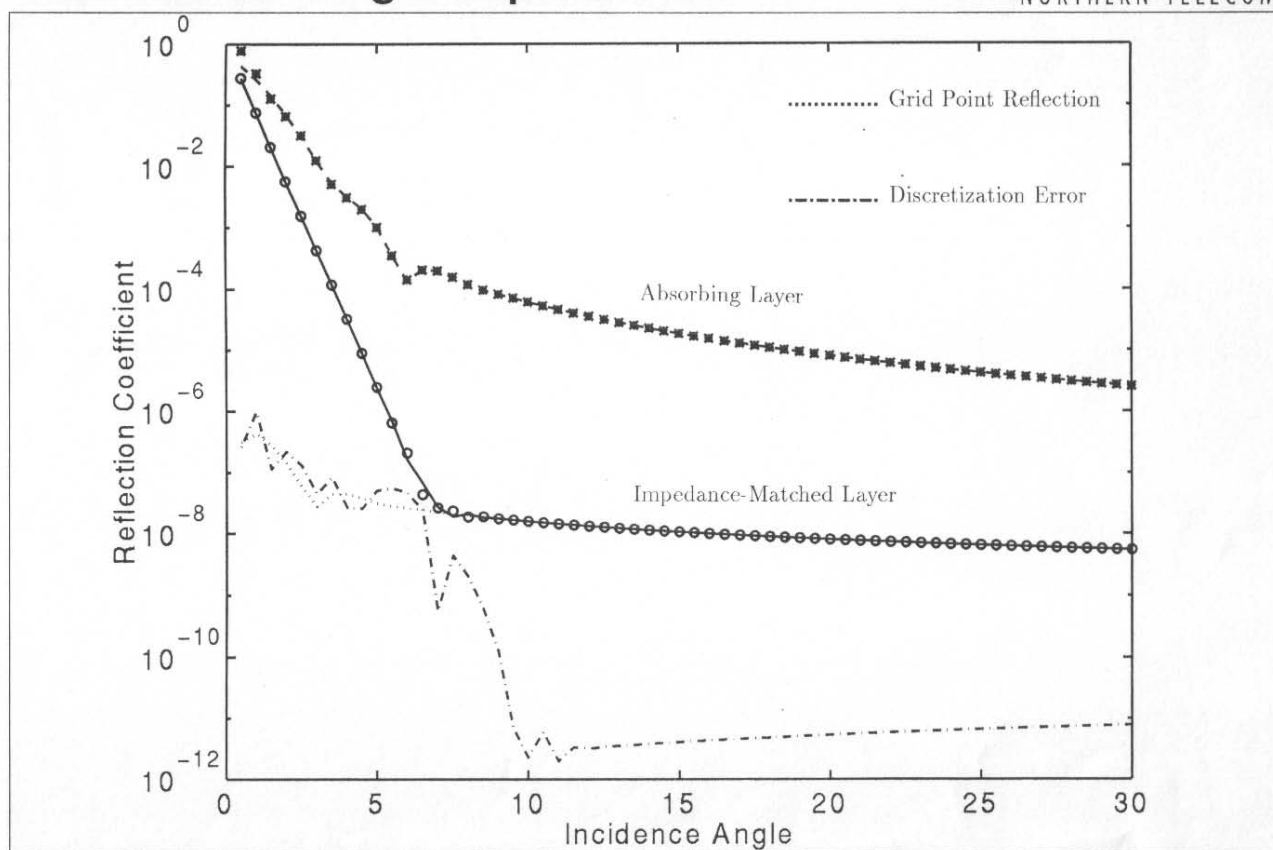


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Approximate and Exact Results

Exact and Approximate Reflection Coefficients - Angle Dependence

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Continuous Nonlocal Boundary

- Assume that $n^2(x_{N-1}) = n^2(x_N) = n_0^2$. At the boundary

$$\frac{\partial^2 E}{\partial x^2} = 2ik_0 n_0 \frac{\partial E}{\partial z}$$

- Crank-Nicholson method - $E_j \equiv E(x, z_j)$

$$\frac{\partial^2}{\partial x^2} \left(\frac{E_{j+1} + E_j}{2} \right) = 2ik_0 n_0 \frac{E_{j+1} - E_j}{\Delta z}$$

- Setting $s \equiv T_{\{-\Delta z\}} = e^{-\Delta z \frac{\partial}{\partial z}}$, we have with $\nu = \sqrt{4ik_0 n_0 / \Delta z}$,

$$\frac{\partial^2 E_{j+1}}{\partial x^2} = \nu^2 \frac{1-s}{1+s} E_{j+1}$$



Continuous Nonlocal Boundary

- Outgoing condition (right boundary)

$$\frac{\partial E_{j+1}}{\partial x} = -\nu \sqrt{\frac{1-s}{1+s}} E_{j+1}$$

With $s^l E(x, z) = E(x, z - l\Delta z)$, we have

$$\begin{aligned} \frac{\partial E(x, z_{j+1})}{\partial x} + \nu E(x, z_{j+1}) = \\ \nu \left[E(x, z_j) - \frac{1}{2}E(x, z_{j-1}) + \right. \\ \left. \frac{1}{2}E(x, z_{j-2}) - \frac{3}{8}E(x, z_{j-3}) + \dots \right]. \end{aligned}$$

- The electric field is optimally evaluated at $(x_{N_w} + x_{N_w+1})/2$.

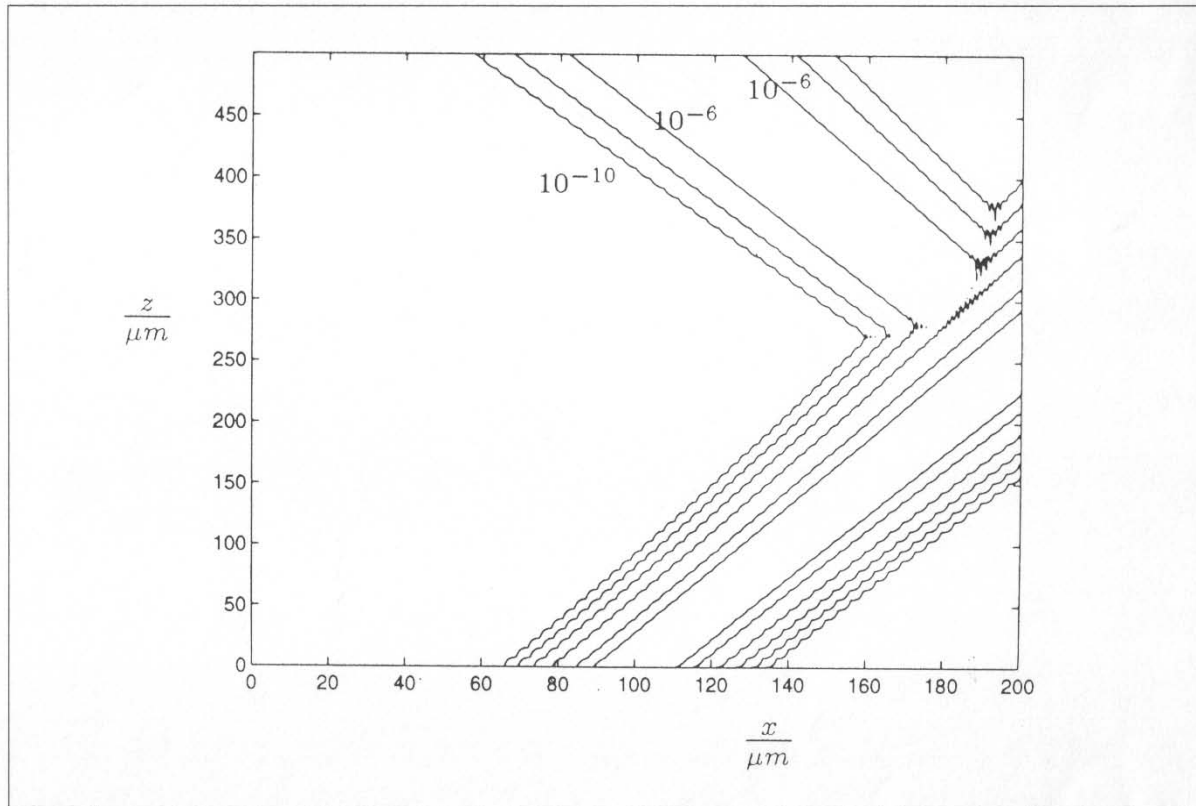


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Gaussian Beam - Continuous N.L.

Continuous Nonlocal Boundary Condition
Gaussian Beam, 1024 Points

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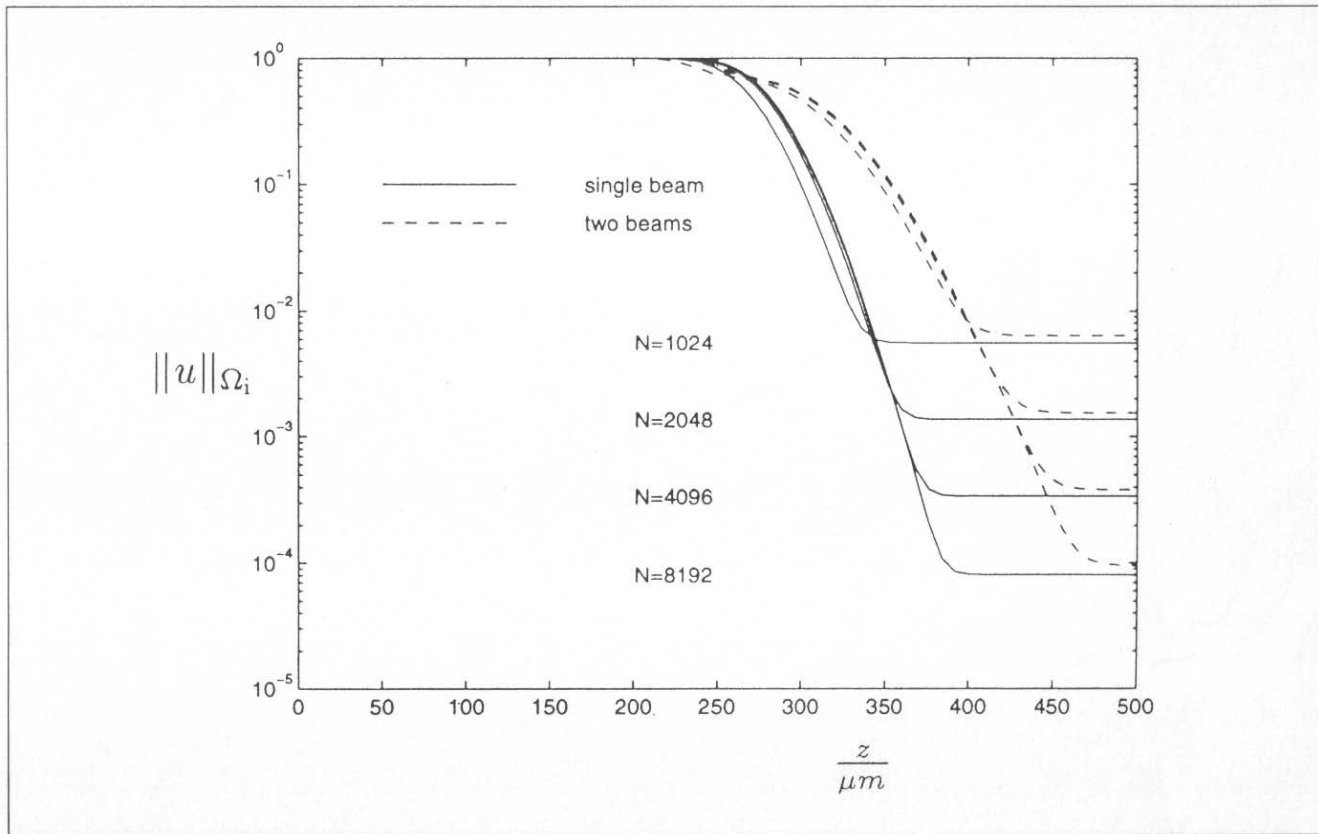


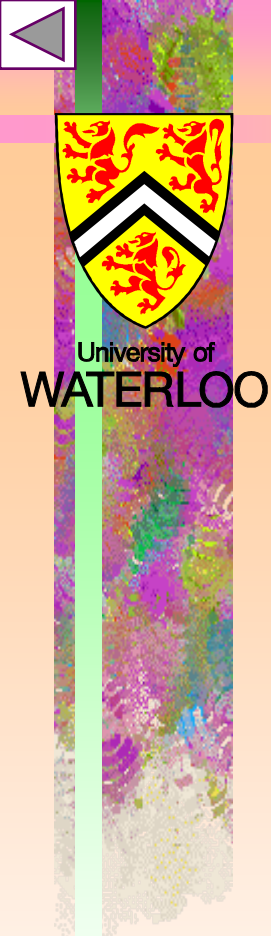


Remaining Power - Continuous

Continuous Nonlocal Boundary Condition
 L_2 Norm, 1 and 2 Gaussian Beams

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Exact Nonlocal Boundary

- With $E_m \equiv E(x_m, z_j + \Delta z)$ the Crank-Nicholson method yields on a discrete grid

$$(1 + s)(E_{m+1} - (2 - k_0^2 \Delta n^2)E_m + E_{m-1}) = \nu^2(1 - s)E_m$$

- Applying the x -translation operator $r \equiv T_{\{-\Delta x\}} = e^{-\Delta x \frac{\partial}{\partial x}}$

$$r^2 - (2 - k_0^2 \Delta n^2)r + 1 = \nu^2 \frac{1 - s}{1 + s} r$$

- If the root with $|r| < 1$ is denoted by r_- , the discrete transparent boundary condition is

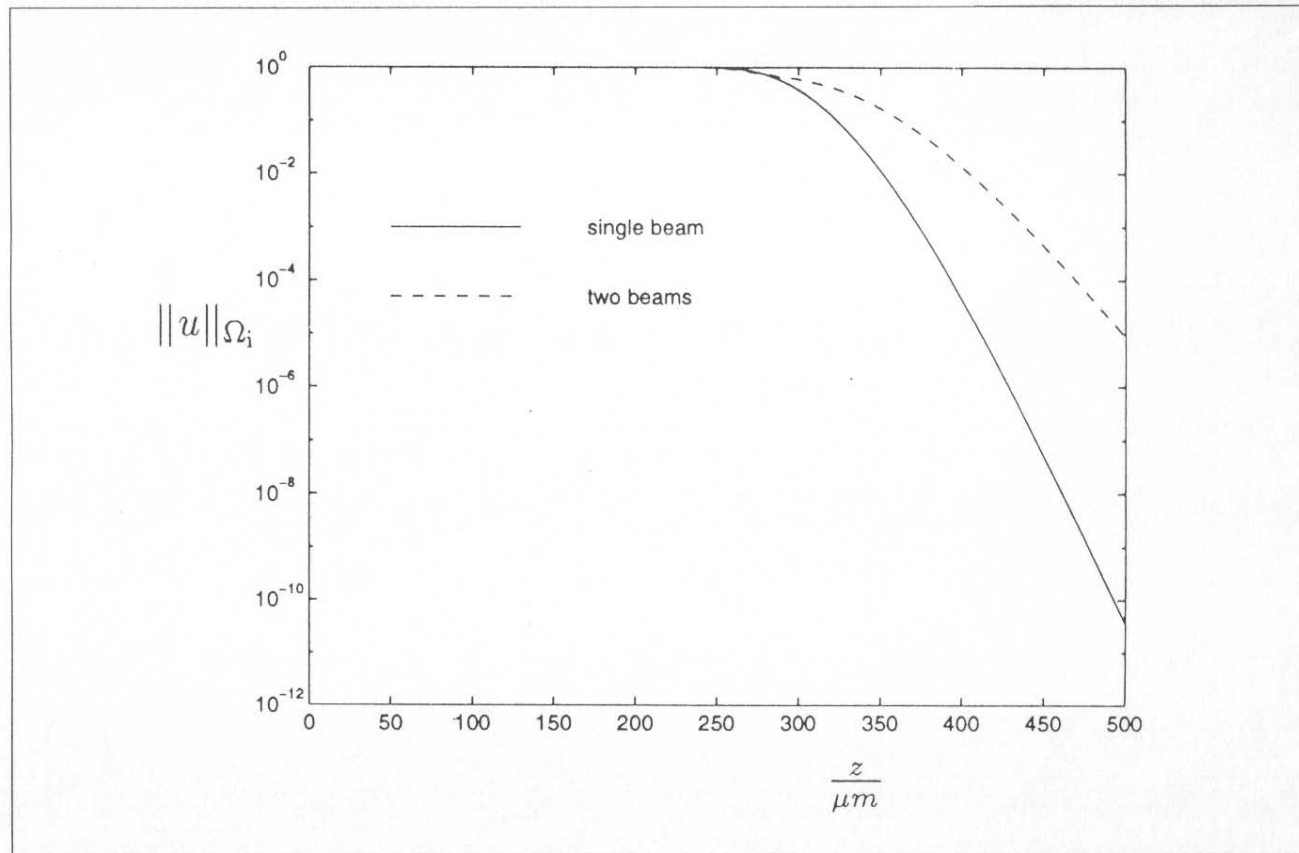
$$E_{N+1} = r_- \cdot E_N$$



Remaining Power - Discrete

Discrete Nonlocal Boundary Condition
 L_2 Norm, 1 and 2 Gaussian Beams

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Padé [1,1] Boundary Conditions

- [1,1] Padé Approximation

$$-1 + \sqrt{1+H} \approx \frac{H/2}{1+H/4}$$

- Claerbout's Equation

$$\left[\left(1 + \frac{H}{4} \right) \frac{\partial}{\partial z} + \delta \frac{H}{2} \right] E(x, y, z) = 0$$

- Boundary Condition Equation ($n_b = n_0$)

$$\left(1 + \frac{X_0}{4} \right) \left[\frac{1-s}{\Delta z} \right] E(z + \Delta z) = -\delta \frac{X_0}{4} (1+s) E(z + \Delta z)$$



Padé [2,0] Boundary Conditions

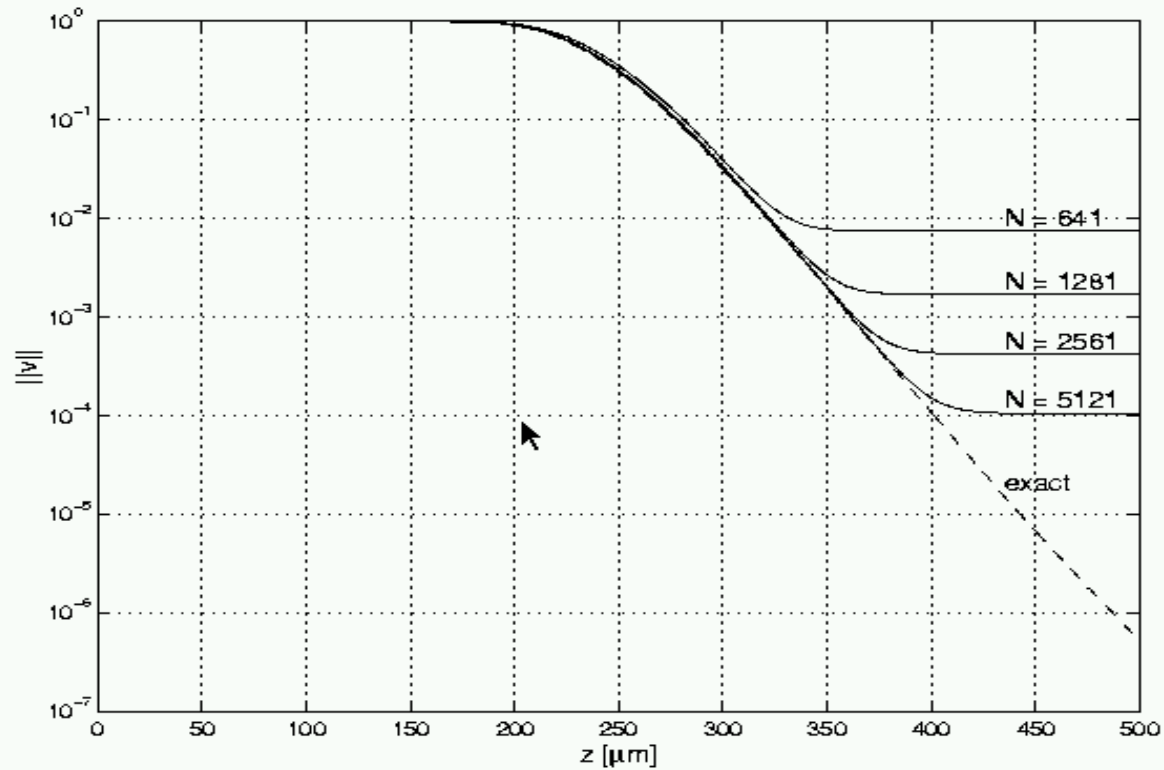
- [2,2] Padé Equation

$$\left(\frac{1-s}{\Delta z}\right)E_{j+1}(x) = -\delta\left(1 + \frac{X_0}{2} - \frac{X_0^2}{8}\right)\left(\frac{1+s}{2}\right)E_{j+1}(x)$$

- Laplace transform this equation with respect to \mathbf{x} in the exterior region.
- Requiring that no poles are present in the right-hand plane of the transform yields the desired boundary condition.



[2,2] Boundary Condition Results





Padé [N,N] Boundary Conditions

- For the [N,N] case, $sE_i(x) = E_{i-1}(x)$, where

$$g_i^{(1)}(x) = \left(\frac{1 - a_1' \partial_x^2}{1 - a_1 \partial_x^2} \right) E_{i-1}(x)$$

$$g_i^{(2)}(x) = \left(\frac{1 - a_2' \partial_x^2}{1 - a_2 \partial_x^2} \right) g_i^{(1)}(x)$$

⋮

$$g_i^{(k-1)}(x) = \left(\frac{1 - a_{k-1}' \partial_x^2}{1 - a_{k-1} \partial_x^2} \right) g_i^{(k-2)}(x)$$

$$E_i(x) = \left(\frac{1 - a_k' \partial_x^2}{1 - a_k \partial_x^2} \right) g_i^{(k-1)}(x)$$



General Boundary Conditions (2)

- Introducing a vector $\mathbf{g}_i(x)$ with $\mathbf{g}_{i,j}(x) = g_i^{(j)}(x)$, $j = 1 \dots k - 1$, $\mathbf{g}_{i,k}(x) = E_i(x)$ yields

$$(\mathbf{E} + \mathbf{A} \partial_x^2) \mathbf{g}_i(x) = 0$$

with boundary conditions

$$\dot{\mathbf{g}}_{i,+} = \mathbf{B}_+ \mathbf{g}_{i,+}, \quad \dot{\mathbf{g}}_{i,-} = \mathbf{B}_- \mathbf{g}_{i,-}$$



General Boundary Conditions (3)

- After Laplace transforming, this yields

$$(\mathbf{E} + p^2 \mathbf{A}) \hat{\mathbf{g}}_i(p) = \mathbf{A}(p \mathbf{g}_{i,0} + \dot{\mathbf{g}}_{i,0})$$

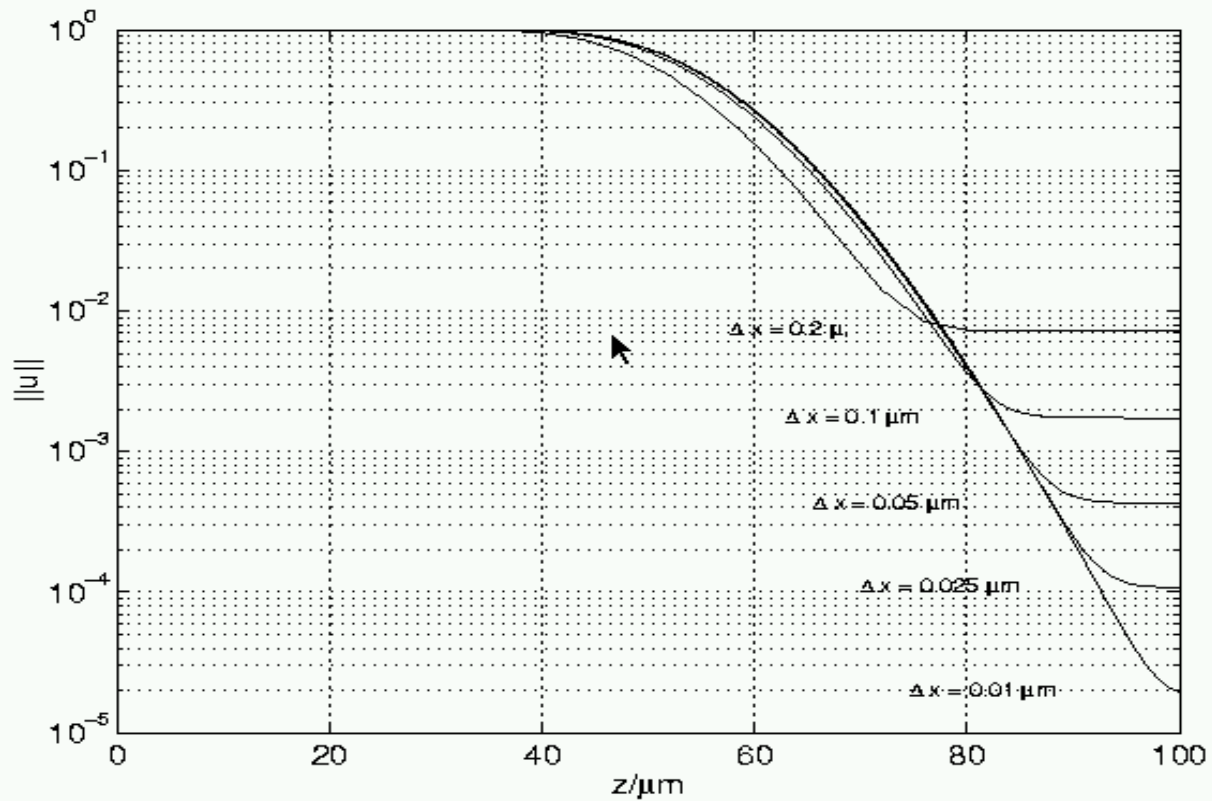
or, defining $\mathbf{C}^2 = -\mathbf{A}^{-1} \mathbf{E}$,

$$(p^2 \mathbf{I} - \mathbf{C}^2) \hat{\mathbf{g}}_i(p) = p \mathbf{g}_{i,0} + \dot{\mathbf{g}}_{i,0}$$

- Problem: Construct \mathbf{C} such that all poles of $(p \mathbf{I} + \mathbf{C})^{-1}$ have $\Re p_j > 0$



[N,N] Boundary Condition Results



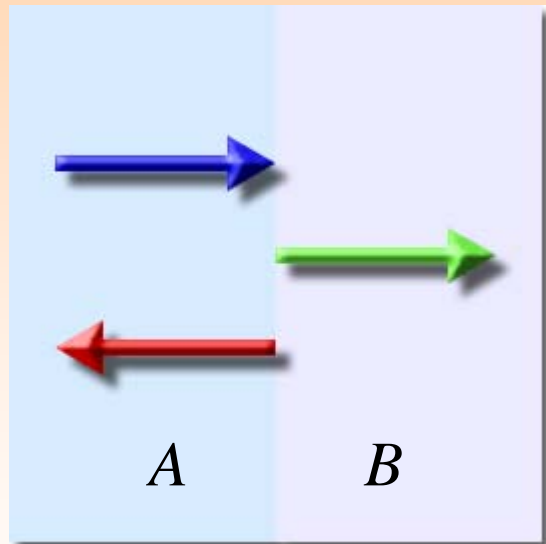


Part III - Improving Accuracy in Fast Reflection Calculations



Facet Reflection Coefficient

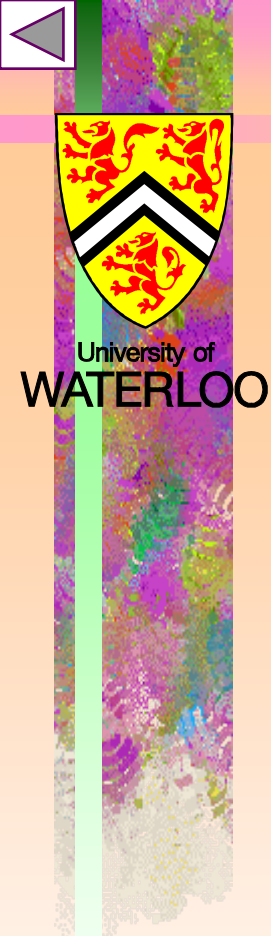
- Matching E_y and $\frac{\partial E_y}{\partial z}$ at the boundary gives



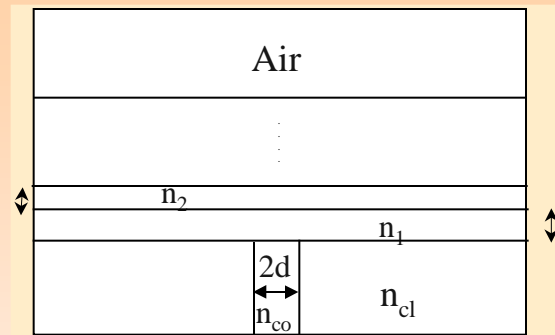
$$\Psi_y = \Psi_o^+ e^{-ik_o n_{ol} L_l z} + \Psi_o^- e^{ik_o n_{ol} L_l z}$$

$$E_{yr}^{(k+1)} = \frac{1}{2} (1 - L_B L_A) (E_{yr}^{(k)} - E_{yi}) , \text{ or}$$

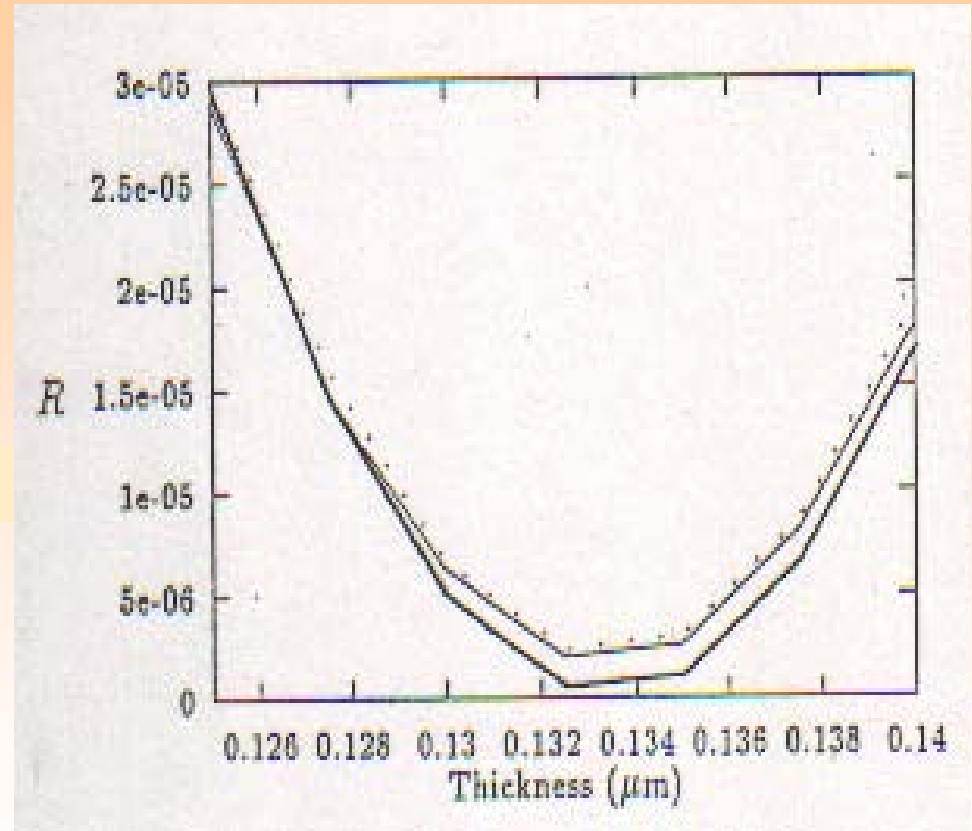
$$[R]_{TE} = \frac{E_{yr}}{E_{yi}} = \frac{n_{oA} L_A - n_{oB} L_B}{n_{oA} L_A + n_{oB} L_B}$$



Reflection Coefficients



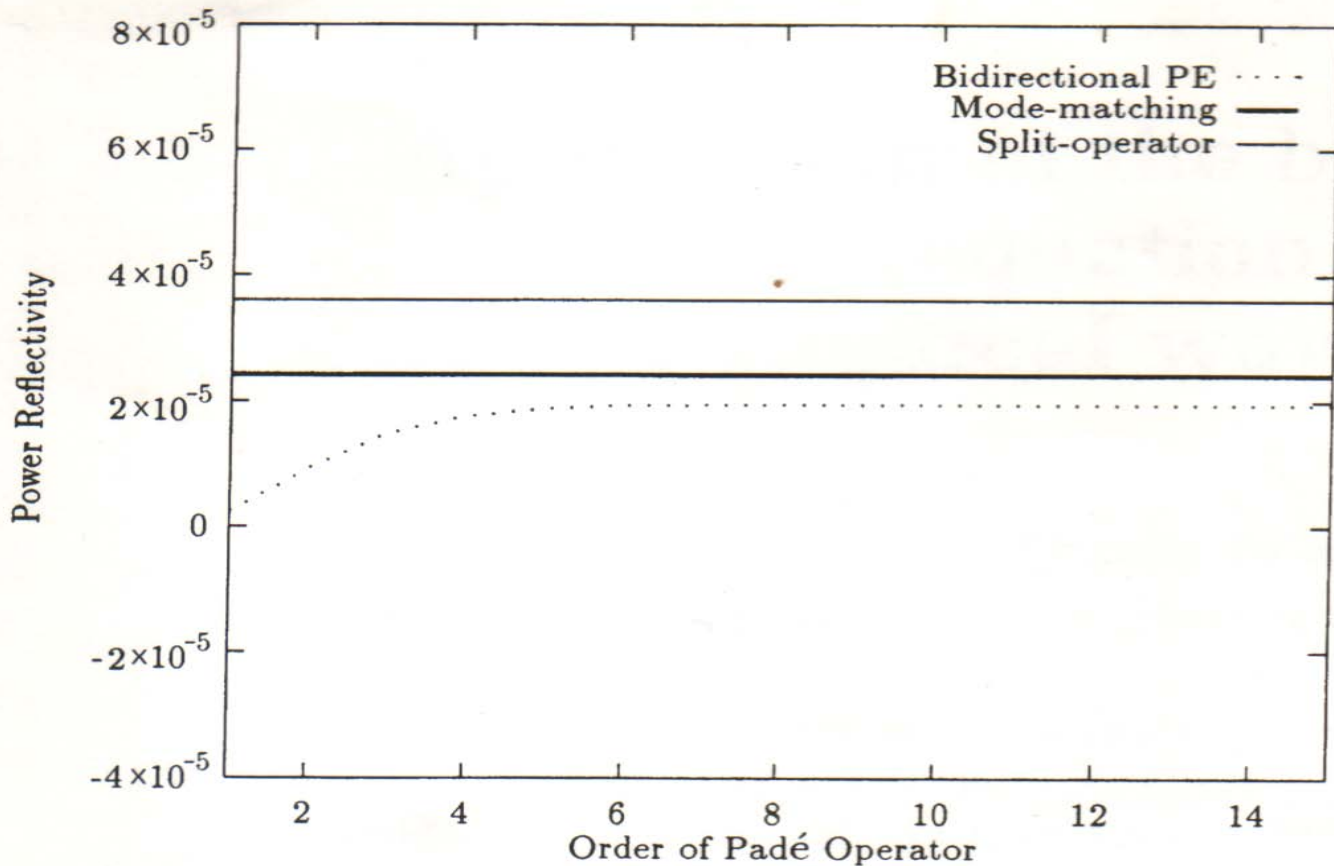
Waveguide Geometry





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Standard Operator Results





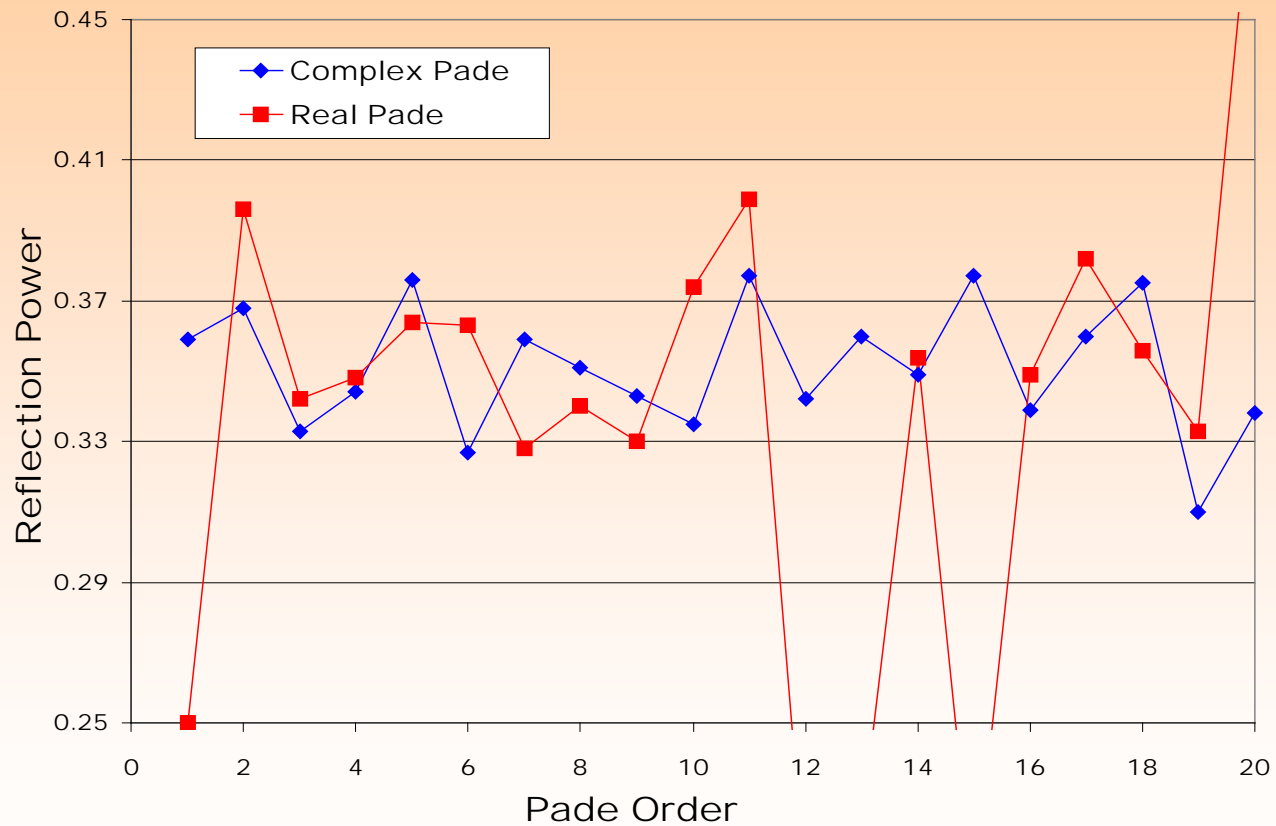
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Calculated Reflection Error

- Since the Padé approximation for L has poles in the evanescent spectral region, uncontrollable errors can develop.
- One method to resolve this - Generate an approximant with complex coefficients by selecting an imaginary termination condition for the continued fraction representation of $\sqrt{1+H}$.



Complex Padé Reflection





Rotated Padé Approximants

- A second method: Write

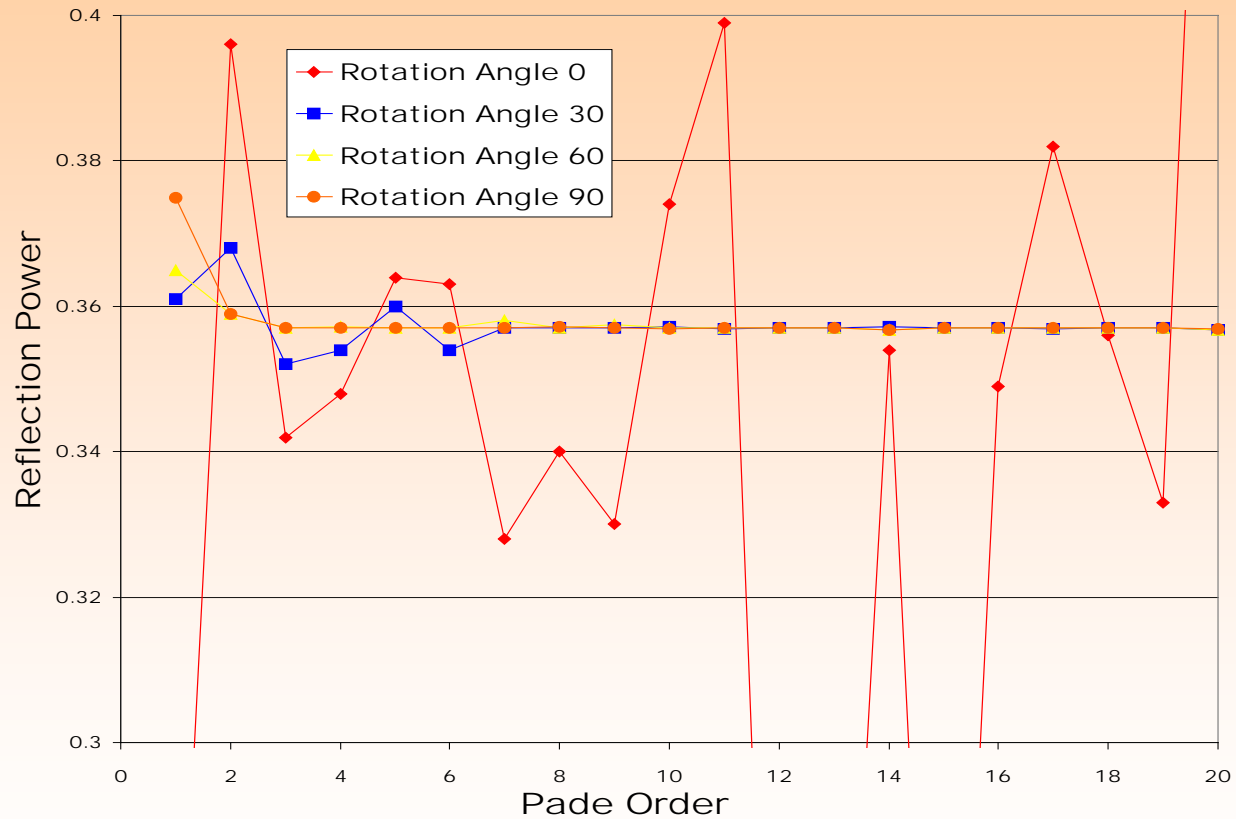
$$\sqrt{1 + H} = e^{i\alpha/2} \sqrt{1 + [(1 + x)e^{-i\alpha} - 1]}$$

and perform a Padé expansion in the variable

$$y = (1 + x)e^{-i\alpha} - 1$$

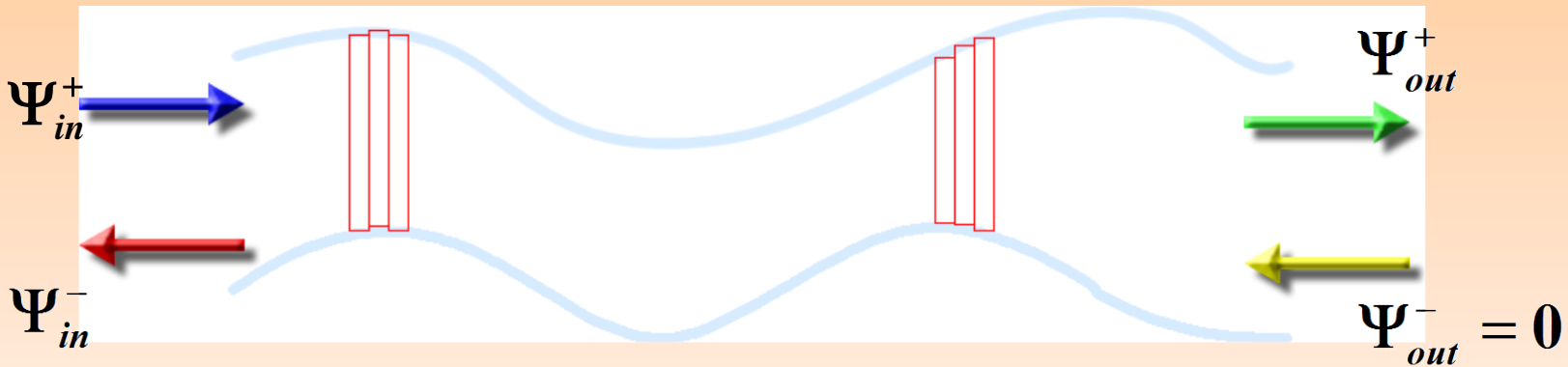


Rotated Padé Reflection





Refractive Index Discretization



$$\begin{pmatrix} \Psi_{out}^+ \\ \Psi_{out}^- \end{pmatrix} = G \begin{pmatrix} \Psi_{in}^+ \\ \Psi_{in}^- \end{pmatrix} \quad G = \begin{pmatrix} g_{11} & g_{12} \\ g_{21} & g_{22} \end{pmatrix} = T_n P_n T_{n-1} P_{n-1} \dots T_2 P_2 T_1 P_1$$

Reflected field

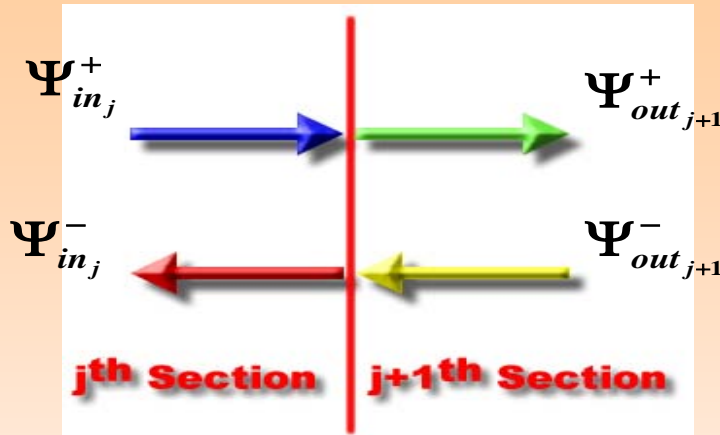
$$\Psi_{in}^- = -g_{22}^{-1} g_{21} \Psi_{in}^+$$

Transmitted field

$$\Psi_{out}^+ = (g_{11} - g_{12} g_{22}^{-1} g_{21}) \Psi_{in}^+$$



Transition, Propagation Operator

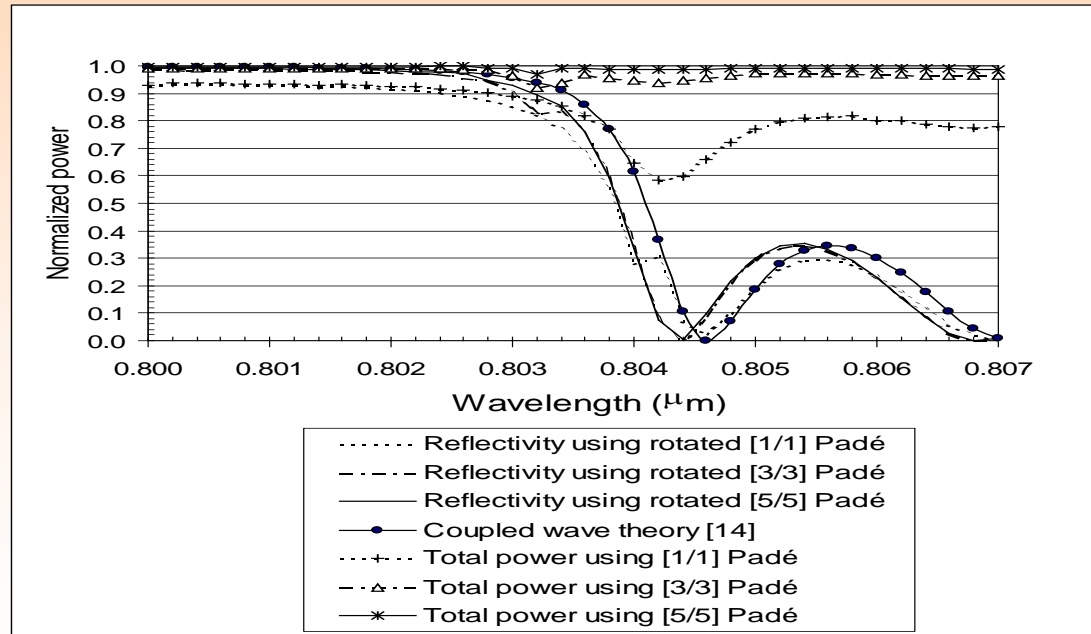
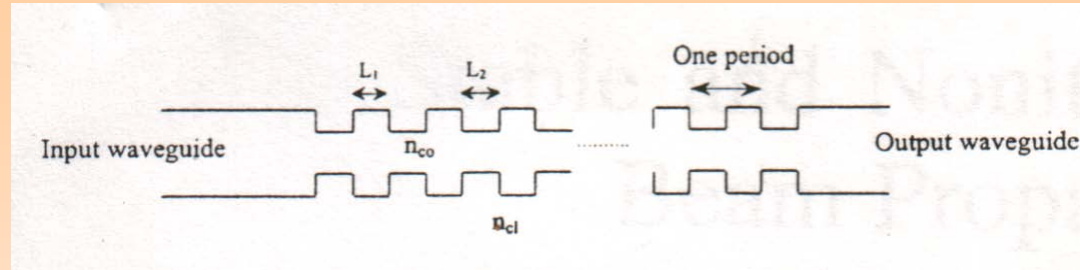


$$P_m = \begin{pmatrix} e^{-jk_o n_{om} L_m z} & \mathbf{0} \\ \mathbf{0} & e^{jk_o n_{om} L_m z} \end{pmatrix}$$

$$T_j = \frac{1}{2} \begin{pmatrix} \mathbf{1} + \frac{n_{o_j}}{n_{o_{j+1}}} L_{j+1}^{-1} L_j & \mathbf{1} - \frac{n_{o_j}}{n_{o_{j+1}}} L_{j+1}^{-1} L_j \\ \mathbf{1} - \frac{n_{o_j}}{n_{o_{j+1}}} L_{j+1}^{-1} L_j & \mathbf{1} + \frac{n_{o_j}}{n_{o_{j+1}}} L_{j+1}^{-1} L_j \end{pmatrix}$$



Distributed Feedback





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Conclusions

- Procedures now exist for constructing exact, nonlocal boundary conditions for wide-classes of two-dimensional parabolic partial differential equations.
- Modified Padé operators can be employed to increase the accuracy of reflection calculations at abrupt interfaces.