

A Neural Network Monte Carlo Evaluation of Withdrawal Benefits in Variable Annuities

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ADVANCES IN PREDICTIVE ANALYTICS

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Introduction

Guaranteed Minimum Withdrawal Benefit (GMWB)

- GMWB: Option to withdraw certain amount every year free of charge, even if account value decreases; in practice offered with step-ups, high-watermark guarantees, fee forgiveness, etc.
- Complex payoff profile. In particular, due to option to withdraw the resulting option valuation problem is non-European – and goes beyond optimal stopping.
- The conventional approach: Numerical methods that require a discretization of the (Markov) state space, such as finite difference schemes. When considering realistic setting?

“Curse of Dimensionality”

Goals

Set up the Problem

- Formulate Pricing Problem of GMWBs
- Specify the Dynamic Optimization Problems

Set up Strategy

- Set up the algorithm to solve the involved dynamic programming
- Explore the feasibility of the Neural Network approach for other (non-surrender) option features (beyond optimal stopping)
- Comparison to grid-based algorithm in Black-Scholes setup

Explore potential limitations...

Set-up

We consider

- d -dimensional Markov process $Y = (Y_t)_{t \in [0, T]}$ drives financial assets and mortality risk
- Possible withdrawal time : $t_i, i = 1, 2, \dots, n - 1$ where

$$0 = t_0 < t_1 < \dots < t_{n-1} < t_n = T,$$

and T is maturity of contract.

- Initial premium P invested in investment funds $S_t = S_t(Y_t)$, and the insurer has a personal (separate) account, X_t .

Set-up (Moenig & Bauer, 2015)

- Law of motion

$$X_{t_i}^+ = \max(0, X_{t_i}^- - w_{t_i}), \quad i = 1, 2, \dots, n-1,$$

$$X_{t_i}^- = X_{t_{i-1}}^+ \frac{S_{t_i}}{S_{t_{i-1}}} e^{-\phi(t_i - t_{i-1})}, \quad i = 1, 2, \dots, n,$$

$$X_{t_0}^+ = P,$$

ϕ : an option fee, w_{t_i} : amount of withdrawal

- Amount of withdrawal

$$0 \leq w_{t_i} \leq \max(X_{t_i}^-, \min(g_{t_i}, G_{t_i})),$$

g_{t_i} : guaranteed amount of withdrawal, G_{t_i} : guarantee account.

Set-up

- Motion of guarantee account

$$G_{t_{i+1}} = \begin{cases} \max(0, G_{t_i} - w_{t_i}), & w_{t_i} \leq g_{t_i} \\ \min\left(\max(0, G_{t_i} - w_{t_i}), \frac{X_{t_i}^+}{X_{t_i}^-} G_{t_i}\right), & w_{t_i} > g_{t_i} \end{cases}$$

with $i = 1, 2, \dots, n - 1$ and $G_{t_1} = P$.

- Cash amount

$$\begin{aligned} C(t_i, w_{t_i}) &= w_{t_i} - \text{fee}_{t_i}^I - \text{fee}_{t_i}^R, \\ \text{fee}_{t_i}^I &= ep_{t_i} \times \max(0, w_{t_i} - \min(g_{t_i}, G_{t_i})), \\ \text{fee}_{t_i}^R &= pg_{t_i} \times (w_{t_i} - \text{fee}_{t_i}^I) \mathbb{1}_{\{x+t_i < 59.5\}}. \end{aligned}$$

- Death Benefit

$$D_{t_i} = \max(X_{t_i}^-, G_{t_i}), \quad i = 1, 2, \dots, n.$$

- Survival Benefit

$$V(T) = \max(X_T^-, \min(g_T, G_T)).$$

Price

The policyholder maximizes the value of contract by finding “optimal” amounts of withdrawal strategy:

$$\begin{aligned}
 V(0) = \sup_{\mathcal{W} \in \mathcal{A}} \mathbb{E}^{\mathbb{P} \times \mathbb{Q}} \left[\right. & \sum_{i=1}^{(n-1) \wedge \tau} e^{-\int_0^{t_i} r_s ds} e^{-\int_0^{t_i} \mu_x(s) ds} C(t_i, w_{t_i}) \\
 & + e^{-\int_0^T r_s ds} e^{-\int_0^T \mu_x(s) ds} V(T) \mathbf{1}_{\{T \geq \tau\}} \\
 & + \sum_{j=1}^{n \wedge \tau} e^{-\int_0^{t_j} r_t dt} e^{-\int_0^{t_j-1} \mu_x(t) dt} \times \\
 & \left. \left(1 - e^{-\int_0^{t_j-t_{j-1}} \mu_{x+t_{j-1}}(t) dt} \right) D_{t_j} \Big| Y_0 \right],
 \end{aligned}$$

where

- \mathcal{A} : family of all conceivable withdrawal strategies,
- $\mathbb{P} \times \mathbb{Q}$: the product measure for biometric \times financial events,
- r_t : risk free interest rate, $\mu_x(t)$: force of mortality,
- τ : surrender time.

Dynamic Programming

Usually not possible to find $V(0)$ analytically

→ **Dynamic Programming Principle:** For $i = n - 1, \dots, 1$,

$$V_{t_i}(Y_{t_i}) = \max_{w_{t_i}} C(t_i, w_{t_i}) + \mathbb{E}^{\mathbb{P} \times \mathbb{Q}} \left[e^{-\int_{t_i}^{t_{i+1}} r_s ds} \left\{ t_{i+1} - t_i p_{x+t_i} V_{t_{i+1}}(Y_{t_{i+1}}) + \left(1 - t_{i+1} - t_i p_{x+t_i} \right) D_{t_{i+1}}(Y_{t_{i+1}}) \right\} \middle| Y_{t_i} \right],$$

subject to

- $0 \leq w_{t_i} \leq \max(X_{t_i}^-, \min(g_{t_i}, G_{t_i}))$
- $V_{t_n}(Y_{t_n})^* = V_{t_n}(Y_{t_n}) = \max(X_{t_n}^-, \min(g_{t_n}, G_{t_n}))$

Problem: How to approximate the
Expectation?

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Problem: How to approximate the
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Neural Network

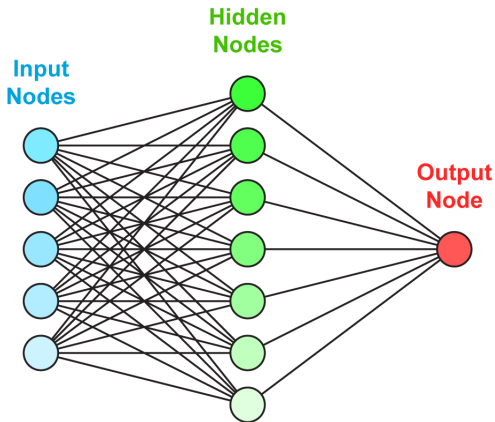


Figure: Simple Neural Networks: the input layer, a hidden layer, and the output layer

Application of NN at t_{n-1}

Assume that

- We have N sample paths of $Y_{t_{n-1}}$ such as fund, interest rate, mortality... and associated V_T and D_T .
- Generate $w_{t_{n-1}}$ which is an element of a **finite** set.
- Generate associated V_T and D_T
- For each $w_{t_{n-1}}$, calculate (noisy) actuarial present values of $V_{t_{n-1}}$ using $w_{t_{n-1}}$, D_T and V_T , denoted by $E_{t_{n-1}}$
- We will use the following set

$$(Y_{t_{n-1}}, E_{t_{n-1}})$$

as a *training set* to fit $E_{t_{n-1}}$ on perceptrons which have Y_{T-1} as inputs.

Then,

- The predicted value of $E_{t_{n-1}}$ based on a trained NN becomes an approximation of $V_{t_{n-1}}$.
- Solve the dynamic programming at t_{n-1} based on the approximated $V_{t_{n-1}}$

Algorithm

- ① At $t_i, i = 1, 2, \dots, n$, generate K sample paths of state variables $Y_{t_i}^{(k)}, k = 1, 2, \dots, K$ and generate *random* $w_{t_i}^{(k)}$ based on $Y_{t_i}^{(k)}$.

- ② At $t_i, i = n - 1, n - 2, \dots, 1$,

- ① Divide and collect sample paths which have the same admissible set.
- ② At each set, collect sample paths which have the same withdrawal strategy.
- ③ Based on the categorized training set, calculate

$$E^{(k)} = d_{t_i}^{(k)} \left(p_{t_i}^{(k)} \tilde{V}_{t_{i+1}}^{(k)}(Y_{t_n}^{(k)}) + (1 - p_{t_i}^{(k)}) \tilde{D}_{t_{i+1}}^{(k)} \right).$$

- ④ Fit $E^{(k)}$ on perceptrons and save fitting results.
- ⑤ Solve the dynamic programming until the maturity and set

$$\begin{aligned} \tilde{V}_{t_i}^{(k)} = & \sum_{h=t_i}^{t_n-1} d_{t_i,h}^{(k)} p_{t_i,h}^{(k)} w_{t_h}^* + \sum_{h=t_{i+1}}^{t_n} d_{t_i,h}^{(k)} (1 - p_{t_i,h}^{(k)}) \tilde{D}(Y_h^{(k)}) \\ & + d_{t_i,t_n}^{(k)} p_{t_i,t_n}^{(k)} \tilde{V}_T^{(k)}(Y_{t_n}^{(k)}) \end{aligned}$$

Discretized solution

When implementing NN,

$\mathcal{A}_{t_i} = \{w_{t_i} | 0 \leq w_{t_i} \leq \max(X_{t_i}^-, \min(g_{t_i}, G_{t_i}))\}$ need to be discretized. We consider:

- $X_{t_i}^- \leq G_{t_i} \leq g_{t_i} \rightarrow A_{t_i} = \{0, X_{t_i}^-, G_{t_i}\},$
- $g_{t_i} \leq G_{t_i} \leq X_{t_i}^-:$
 - $\sum_{s=t_i}^{t_n} g_s < G_{t_i} \rightarrow A_{t_i} = \{0, G_{t_i} - g, X_{t_i}^-\},$ where
 $g = G_{t_i} - \sum_{s=t_{i+1}}^{t_n} g_s$
 - $\sum_{s=t_i}^{t_n} g_s \geq G_{t_i} \rightarrow A_{t_i} = \{0, g_{t_i}, X_{t_i}^-\},$
- $g \leq X_t^- \leq G_t:$
 - $\sum_{s=t_i}^{t_n} g_s < G_{t_i} \rightarrow A_{t_i} = \{0, g, X_{t_i}^-\},$ where
 $g = X_{t_i}^- - X_{t_i}^- / G_{t_i} \left(\sum_{s=t_{i+1}}^{t_n} g_s \right),$
 - $g(T-t) \geq G_t \rightarrow A_{t_i} = \{0, g_{t_i}, X_{t_i}^-\}.$

Contract Under the Black-Scholes Assumption

GMWB contract	
Maturity	15
Number of withdrawal per year	1
Initial Premium (P_0)	15
ep_{t_i}	(8%, 7%, ..., 2%, 1%, 0%, ..., 0%)
pg_{t_i}	10%
g	1
Policyholder	
Age	55
μ	0.01
Financial Market	
Risk free rate	5%
Volatility	15%

Table: Description of GMWB contract under Black-Scholes Assumption

Considered model under Black-Scholes Assumption

State Variables: X_t and G_t

NN model: A skip-layer feedforward neural network:

$$\hat{E}(Y_t) = \alpha + \sum_{j=1}^p \beta_j Y_{t,j} + \sum_h \varphi_h \left(\alpha_h + \sum_{j=1}^p w_{j,h} Y_{t,j} \right)$$

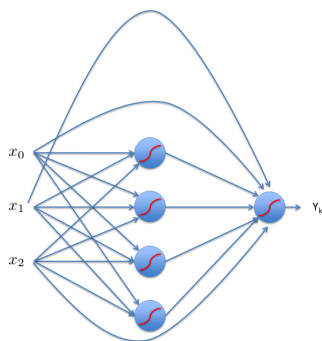


Figure: Input layers are directly sent to the output layer.

Estimation

Usually, the NN algorithm has a over-fitting problem. To find a good number of perceptrons and avoid over-fitting,

- we construct a grid of number of perceptrons and regularization parameters.
- at t_i , the network is trained at each grid point and the best combination is chosen based on RMSE.
- of course, it is time consuming. Is it possible to determine a regularization parameter automatically? (Cherkassky & Ma, 2004 for SVM)

Results

- Number of Simulation: 50,000
- Number of perceptrons and regularization parameters vary at each time
- Option Fee: 0.22%
- Grid : 14.9748
- NNMC: 15.0865
- At certain t_i close to $t_1 = 1$, NNMC seems not to be able to solve the dynamic programming due to overfitting...

Results

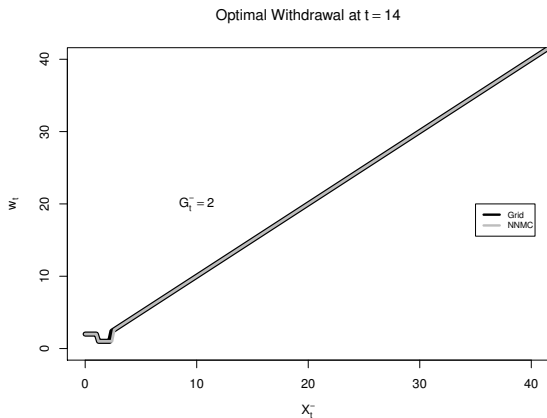


Figure: Optimal Solution via MCNN at $t = 14$ with $G_{14} = 2$. Also, GAM, SVM, MARS are good, but polynomial regressions with regularization are not useful.

Results

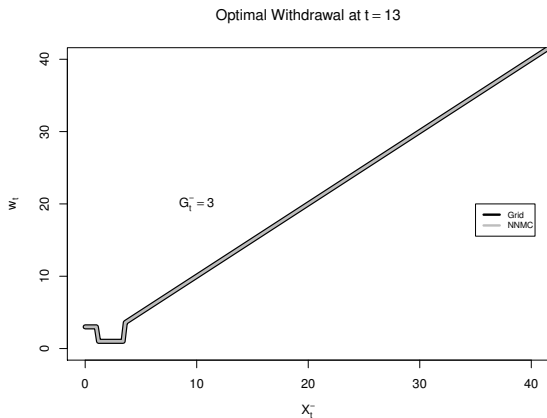


Figure: Optimal Solution via MCNN at $t = 13$ with $G_{13} = 3$. Also, GAM, SVM, MARS are good, but polynomial regressions with regularization are not useful.

Results

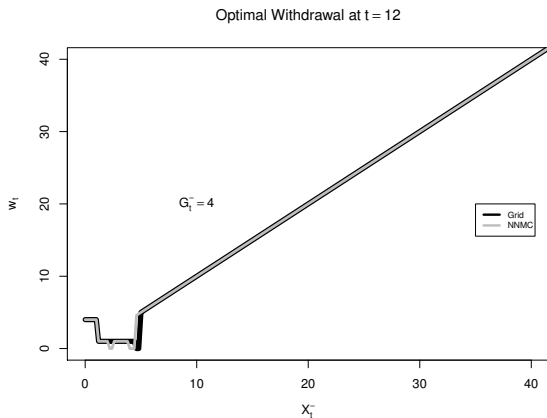


Figure: Optimal Solution via MCNN at $t = 12$ with $G_{12} = 4$. Also, GAM, SVM, MARS are good, but polynomial regressions with regularization are not useful.

Results

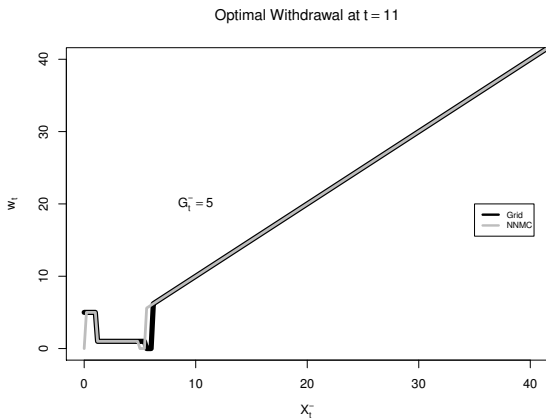


Figure: Optimal Solution via MCNN at $t = 11$ with $G_{11} = 5$. Also, GAM, SVM, MARS are good, but polynomial regressions with regularization are not useful.

Results

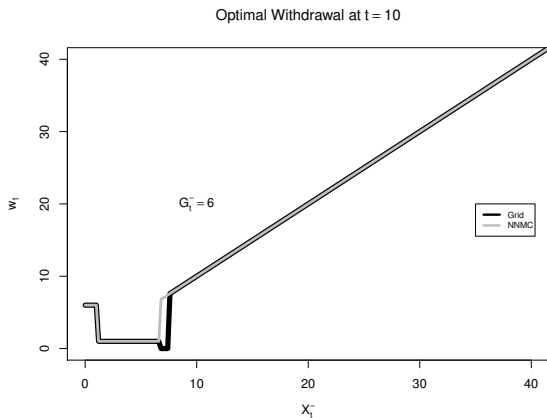


Figure: Optimal Solution via MCNN at $t = 10$ with $G_{10} = 6$. Also, GAM, SVM, MARS are good, but polynomial regressions with regularization are not useful.

Results

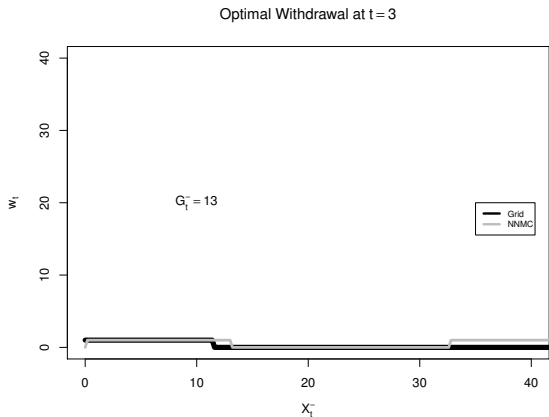


Figure: Optimal Solution via MCNN at $t = 3$ with $G_3 = 13$. We found that the Ridge regression with second order performs better.

Results

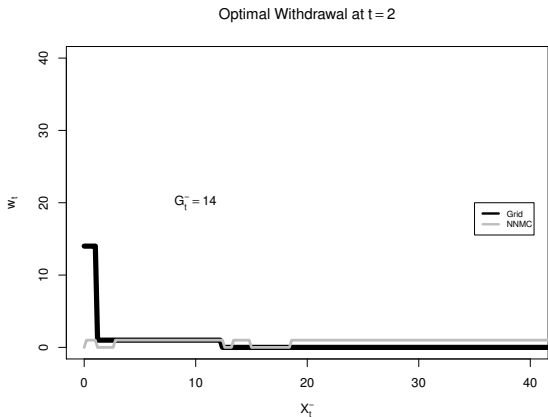


Figure: Optimal Solution via MCNN at $t = 2$ with $G_2 = 14$. We found that the Ridge regression with second order performs better.

Results

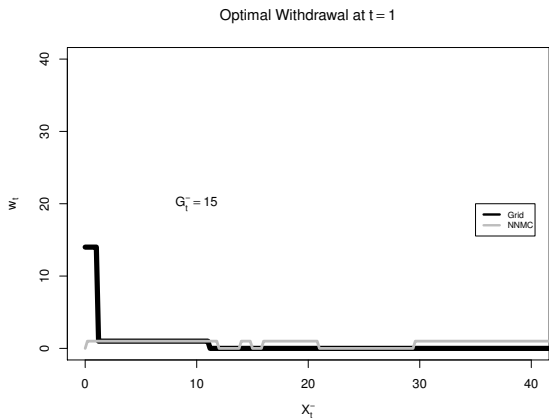


Figure: Optimal Solution via MCNN at $t = 1$ with $G_1 = 14$. We found that the Ridge regression with second order performs better.

Conclusion

- NNMC gives viable results if there is not much noise.
- How can one obtain a robust predictive model?
- *Ensembles* may be a solution to have a right prediction.
- I am implementing *ensembles* with NN, GBM, GAM and LASSO (any suggestions?) to solve dynamic programming based on h2o platform:

<https://www.h2o.ai/>

- It is essential to consider stochastic volatility, stochastic interest rate and stochastic mortality (nontrivial application of machine learning methods).

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Thank you!