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My Journey to Data Mining

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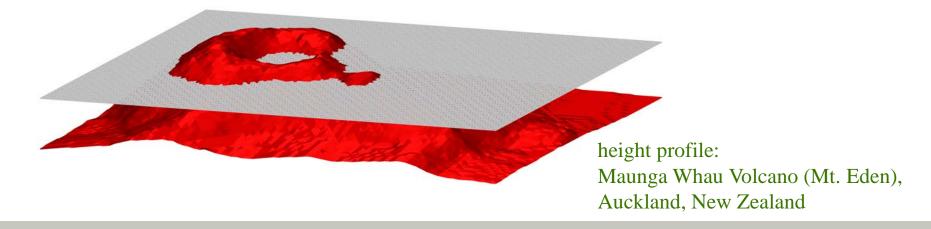


In the beginning...



• spatial databases – spatial data mining



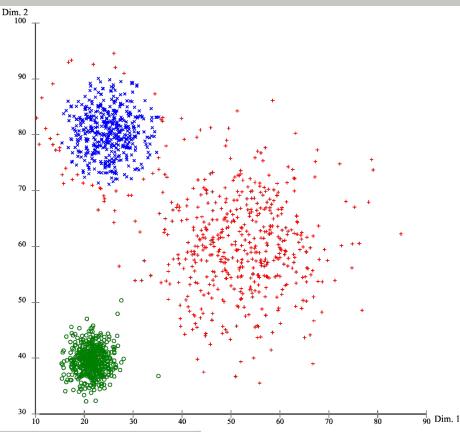




Density-based Clustering: Intuition



- probability density function of the data
- threshold at high probability density level
- cluster of low probability density disappears to noise



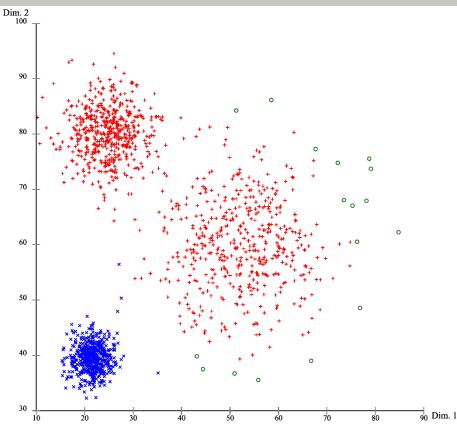
probability density function



Density-based Clustering: Intuition



- low probability density level
- 2 clusters are merged to 1



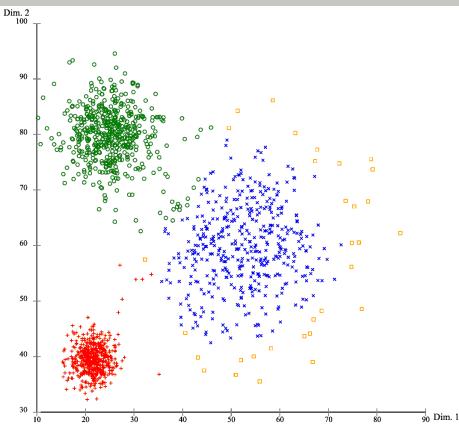
probability density function



Density-based Clustering: Intuition



- medium (good) probability density level
- 3 clusters are well separated









minPts = 5

DBSCAN: Density-Based Spatial Clustering of Applications with Noise

[Ester, Kriegel, Sander, Xu KDD 1996]



- Core points have at least *minPts* points in their ε -neighborhood
- Density connectivity is defined based on core points
- Clusters are transitive hulls of density-connected points





- DBSCAN received the 2014 SIGKDD Test of Time Award
- DBSCAN Revisited: Mis-claim, Un-Fixability, and Approximation [Gan & Tao SIGMOD 2015]
 - Mis-claim according to Gan & Tao:
 DBSCAN terminates in O(n log n) time.
 DBSCAN actually runs in O(n²) worst-case time.
 - Our KDD 1996 paper claims:
 - DBSCAN has an "average" run time complexity of O(n log n) for range queries with a "small" radius (compared to the data space size) when using an appropriate index structure (e.g. R*-tree)
 - The criticism should have been directed at the "average" performance of spatial index structures such as R*-trees and not at an algorithm that uses such index structures





- Contributions of the SIGMOD 2015 paper (apply only to Euclidean distance)
- 1. Reduction from the USEC (**U**nit-**S**pherical Emptiness Checking) problem to the Euclidean DBSCAN problem \rightarrow lower bound of Ω ($n^{4/3}$) for the time complexity of every algorithm solving the Euclidean DBSCAN problem in $d \geq 3$
- 2. Proposal of an approximate grid-based DBSCAN algorithm for Euclidean distance running in O(n) expected time





 DBSCAN Revisited, Revisited: Why and how you should (still) use DBSCAN [E. Schubert, Sander, Ester, Kriegel, Xu, to appear in ACM TODS, 2017]



- Experiments in the SIGMOD 2015 paper not of practical value
- Parameter ε for the range queries was chosen much too large \Rightarrow the approximate algorithm puts all objects into 1 cluster
- Extensive experiments show that for adequate choice of ε, the original DBSCAN algorithm with an R*-tree index outperforms the SIGMOD'15 approximate algorithm





 DBSCAN Revisited, Revisited: Why and how you should (still) use DBSCAN [E. Schubert, Sander, Ester, Kriegel, Xu, to appear in ACM TODS, 2017]



- Lessons learnt from SIGMOD 2015 and ACM TODS 2017:
 - Lower bound of Ω ($n^{4/_3}$) for the time complexity of any algorithm solving the Euclidean DBSCAN problem (SIGMOD 2015)
 - Original DBSCAN algorithm is still the method of choice (ACM TODS 2017)





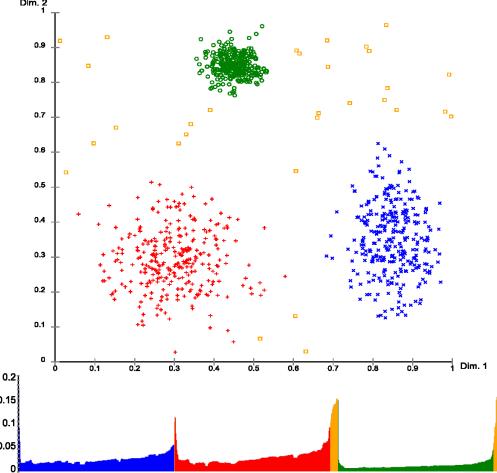
- OPTICS: Ordering Points To Identify the Clustering Structure [Ankerst, Breunig, Kriegel, Sander SIGMOD 1999]
- ordering of the database representing its densitybased clustering structure







suitable for data of different ^{0.2}
 local densities and for ^{0.15}
 hierarchical clusters ^{0.05}

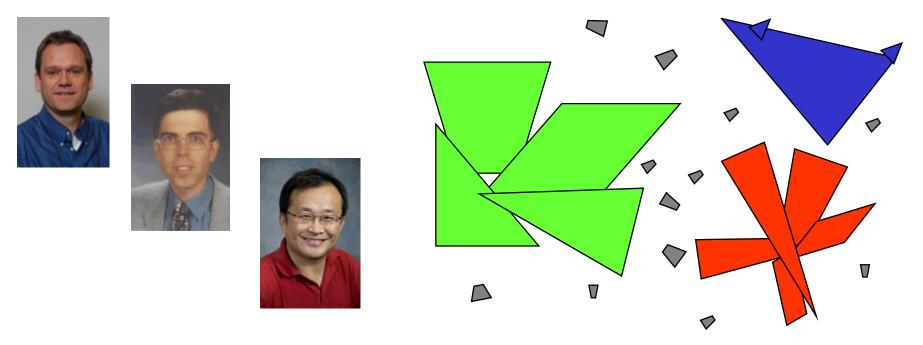




Variants of Density-based Clustering



• GDBSCAN: Generalized DBSCAN [Sander, Ester, Kriegel, Xu DMKD Journal 1998]



clusters point objects as well as spatially extended objects according to spatial and non-spatial attributes and more...





• recent survey on density-based clustering:

H.-P. Kriegel, P. Kröger, J. Sander, A. Zimek: Density-based clustering. Wiley Interdisciplinary Reviews: Data Mining and Knowledge Discovery, 1(3): 231–240, 2011.





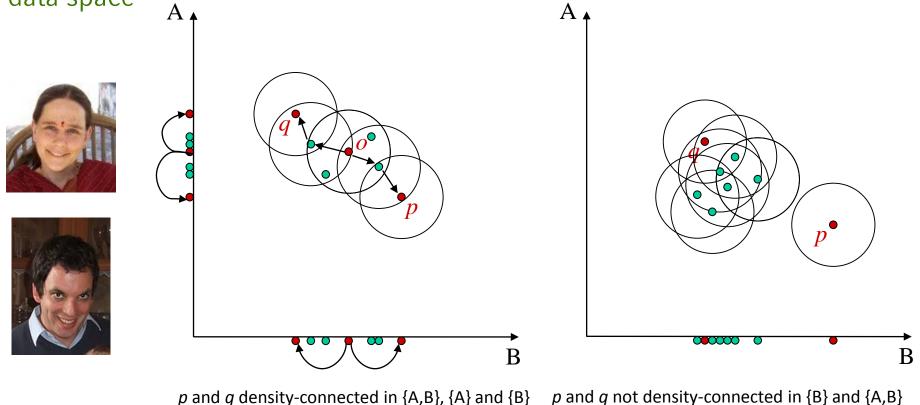




Subspace Clustering in Highdimensional data spaces



 SUBCLU: Density-Connected SUBspace CLUstering for High-Dimensional Data [Kailing, Kriegel, Kröger SDM 2004]
 discovers dense clusters in axis-parallel subspaces of the high-dimensional data space

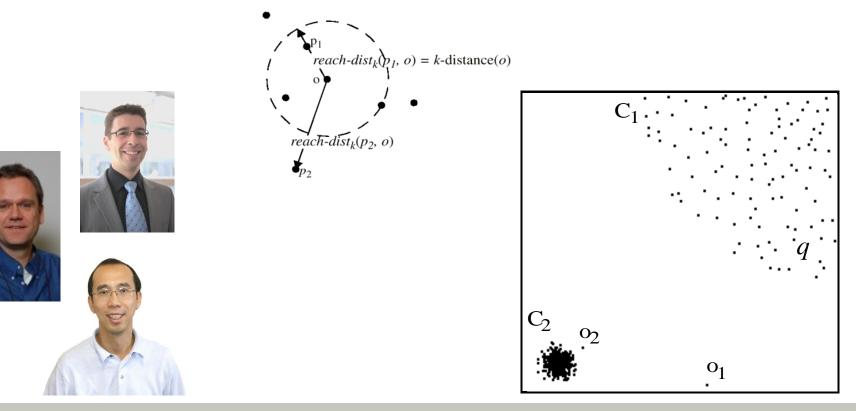




Outlier Detection



- LOF (Local Outlier Factor): Density-based, local outlier detection [Breunig, Kriegel, Ng, Sander SIGMOD 2000]
- quantifies how outlying an object is in its local neighborhood

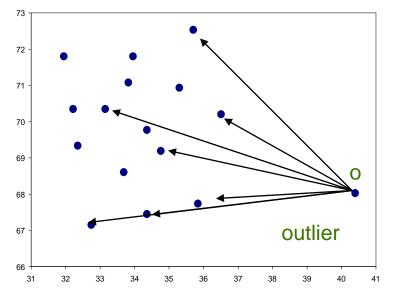


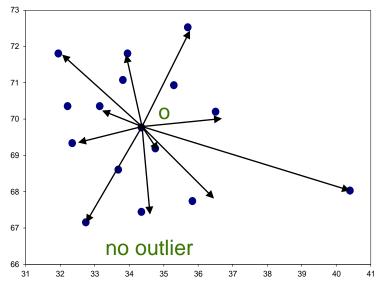


High-dimensional Outlier Detection



• ABOD: Angle-Based Outlier Degree [Kriegel, M. Schubert, Zimek SIGKDD 2008]





- variance of the angles of the potential "outlier" to pairs of points
- angles are more stable than distances in highdimensional spaces



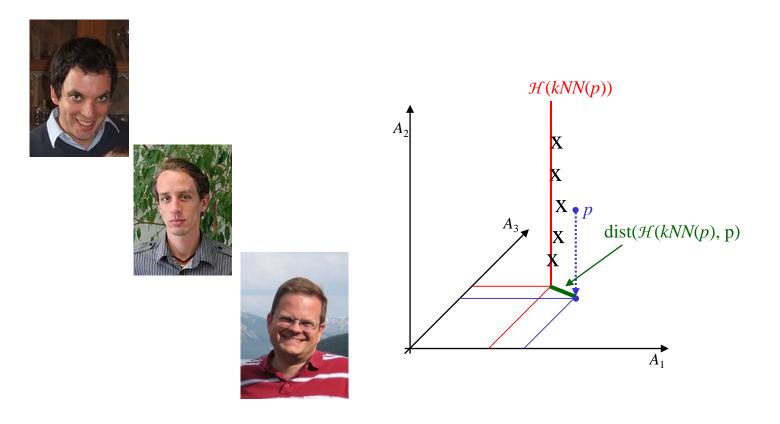




Subspace Outlier Detection



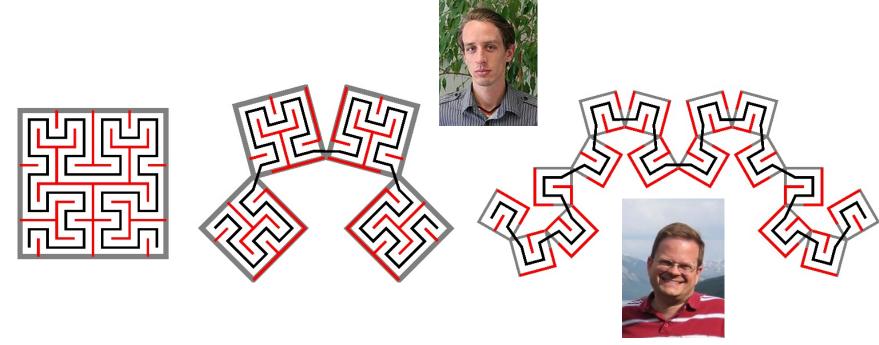
- SOD: Subspace Outlier Degree [Kriegel, Kröger, E. Schubert, Zimek PAKDD 2009]
- detects outliers in subspaces of the high-dimensional data space







- Fast and Scalable Outlier Detection with Approximate Nearest Neighbor Ensembles [E. Schubert, Zimek, Kriegel DASFAA 2015]
 - avoids pairwise comparison of objects to compute nearest neighbors
 - computes nearest neighbors in near-linear time using an ensemble of space-filling curves

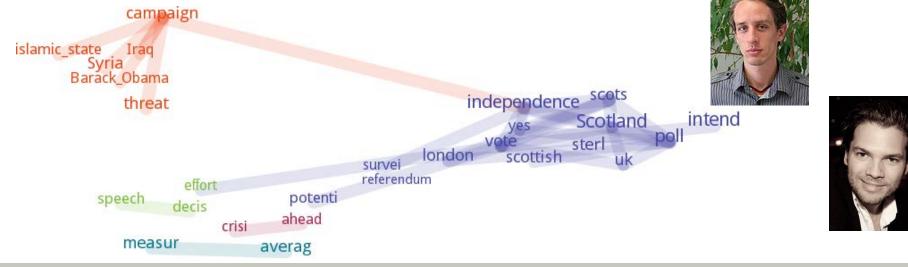




Trend Detection



- SigniTrend: Scalable Detection of Emerging Topics in Textual Streams by Hashed Significance Thresholds [E. Schubert, Weiler, Kriegel SIGKDD 2014]
 - introduces a new significance measure using outlier detection
 - tracks all keyword pairs using hash tables in a heavy-hitter type algorithm
 - aggregates the detected co-trends into larger topics using clustering



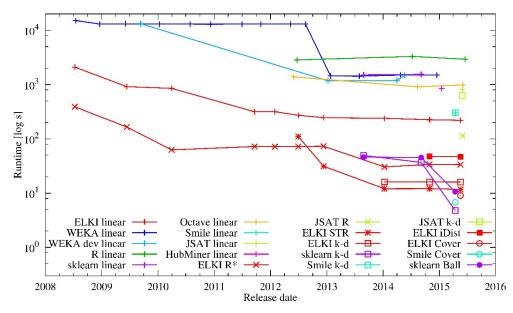


Runtime Evaluation

 The (Black) Art of Runtime Evaluation: Are we comparing (data mining) algorithms or implementations?

[Kriegel, E. Schubert, Zimek KAIS Journal, 1-38, 2016]

- extensive study of runtime behavior of several algorithms (single-link, DBSCAN, k-means, LOF)
- implementation details often dominate algorithmic merits
- the same algorithm can exhibit runtime differences of two orders of magnitude and more in different implementations











Runtime Evaluation



- For more realistic comparisons, all algorithms should be implemented
 - in the same framework, in the same version
 - at the same level of generality, modularization, and optimization
 - using the same backing features (DB layer, index structures)
 and all algorithms should be suitably parameterized.
- We should
 - compare the behavior of algorithms in scalability experiments, not in single absolute runtime values,
 - demonstrate at which point (data set size, dimensionality, parameter values) the asymptotic behavior kicks in.



Tutorials and Surveys



- Subspace clustering, clustering high-dimensional data [Kriegel, Kröger, Zimek]
 - Tutorials at ICDM, KDD, VLDB, PAKDD
 - Survey ACM TKDD 2009
- Outlier detection





- Tutorials at PAKDD, KDD, SDM [Kriegel, Kröger, Zimek]
- Outlier detection in high-dimensional data [Zimek, E. Schubert, Kriegel]:
 - Tutorials at ICDM, PAKDD
 - Survey Statistical Analysis and Data Mining 2012







Implementations



- all these algorithms (and many more) are available in the ELKI framework: http://elki.dbs.ifi.lmu.de/
- ELKI is a java framework, integrating fast data management (e.g., indexing) and many data mining algorithms in a flexible way









release 0.6:

Elke Achtert, Hans-Peter Kriegel, Erich Schubert, Arthur Zimek: Interactive Data Mining with 3D-Parallel-Coordinate-Trees. Proceedings of the ACM International Conference on Management of Data (SIGMOD), New York City, NY, 2013. *(release of version 0.7.1 at VLDB 2015)*





Thank You!