Instructor: Prof. Daniel Miller (EIT3116; ext. 35215; miller@uwaterloo.ca)

Schedule for Fall 2019: Lectures: Monday 2:30pm - 5:30pm (EIT3151)

Calendar Description: An introduction to control theory for linear time-invariant finite-dimensional systems from both the state-space and input-output viewpoints. State-space theory: the concepts of controllability, observability, stabilizability, and detectability; the pole-assignment theorem; observers and dynamic compensation; LQR regulators. Input-output theory: the ring of polynomials and the field of rational functions; the algebra of polynomial and rational matrices; coprime factorization of transfer matrices; Youla parametrization. Introduction to optimal control.

Text: I will provide coursenotes on LEARN; I will place some relevant textbooks on reserve in the library.

Grading:

• There will be exercises spread throughout the notes. Depending on the size of the class, I will mark some of them to yield an assignment mark (25%).

• There will be a midterm worth 25%.

• There will be a final exam worth 50%.

Assumed Background: ECE380 (or equivalent) and familiarity with basic linear algebra.
Detailed Description:

1. **Introduction to Linear Multivariable Systems**
   Some detailed examples include electrical systems and mechanical systems, including an inverted pendulum.

2. **Mathematical Preliminaries**
   Vector spaces, matrices, matrix manipulations, norms, solving linear differential and difference vector equations.

3. **Multivariable LTI Systems: An Input-Output Approach**
   State-space to transfer function, similarity transformations, discretizing a continuous-time system, poles and zeros of a multivariable system.

4. **Controllability**
   Controllability, reachability, PBH test, equivalence of pole placement and controllability, controllable canonical form.

5. **Observers and Observability**
   Observability, detectability, PBH test, observers, separation principle.

6. **LQR Optimal Control**
   Cost functions, dynamic programming, Riccati equation, optimal LQR feedback, properties of the optimal LQR feedback.

7. **Youla Parametrization and its Applications**
   Matrix fractional descriptions of transfer functions, Bezout identity, parametrization of all stabilizing controllers, an introduction to $L_1$, $H_\infty$ and $H_2$ optimal control.
General UW Guidelines

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Discipline: A student is expected to know what constitutes academic integrity - check www.uwaterloo.ca/academicintegrity/ to avoid committing an academic offence, and to take responsibility for his/her actions. A student who is unsure whether an action constitutes an offence, or who needs help in learning how to avoid offences (e.g., plagiarism, cheating) or about rules for group work/collaboration should seek guidance from the course instructor, academic advisor, or the undergraduate Associate Dean. For information on categories of offences and types of penalties, students should refer to Policy 71, Student Discipline, www.adm.uwaterloo.ca/infosec/Policies/policy71.htm. For typical penalties check Guidelines for the Assessment of Penalties, www.adm.uwaterloo.ca/infosec/guidelines/penaltyguidelines.htm.

Appeals: A decision made or penalty imposed under Policy 70 (Student Petitions and Grievances) (other than a petition) or Policy 71 (Student Discipline) may be appealed if there is a ground. A student who believes he/she has a ground for an appeal should refer to Policy 72 (Student Appeals) www.adm.uwaterloo.ca/infosec/Policies/policy72.htm.

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