

Enhancing Learning Outcomes: Exploring the Role of Cognitive Skills when Children Teach a Robot

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INTRODUCTION

RESULTS

Fig 1. Mean level differences between each condition and learning outcomes

- Children demonstrate increased learning when they teach others versus learning for themselves.¹
- Social robots, including when in the role of a tutee, have been used to enhance children's learning outcomes.²
- Different robot characteristics have impacted children's engagement and learning from social robots.³
- However, there is a gap of research examining how children's individual characteristics relate to learning in the context of teaching a robot, as well as whether these associations differ by robot behaviour.

RESEARCH GOAL

To examine children's learning outcomes (increased knowledge, reflection on teaching and learning) after teaching a robot, in relation to:

- The robot's behaviour (type of mistakes)
- The children's cognitive skills, namely, executive functioning (EF) and verbal skills
- An interplay between children's cognitive skills and robot mistake behaviour

METHOD

MEASURES

- Executive Functioning: Children's Executive Functioning Inventory (CHEXI)⁴, a 24item parent-report measure of children's difficulties with EF in everyday contexts.
- Verbal skills: NIH Toolbox Picture Vocabulary Test, a task-based assessment of children's vocabulary comprehension.

PROCEDURE

• Children taught a novel classification to a humanoid robot, namely teaching where aliens were from based on physical characteristics using a classification



2. Participants were randomly assigned to one of three robot conditions:

Correct – Robot made no errors errors on taught material errors on untaught material

- 3. Childs' knowledge of the classification scheme was tested after the teaching task.
- 4. Children provided self-assessments of their teaching and learning using a 5-point Likert scale:
 - 1 I think I was a bad teacher \rightarrow 5 I think I was a great teacher
 - 1 I did not learn at all \rightarrow 5 I learnt a great deal

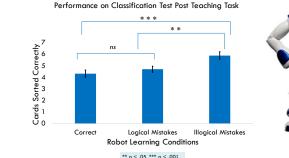


Table 1. Correlations with measures, learning, and self-assessment

ALL CHILDREN Measure	Learning	Self-assessment		
	Classification Task Knowledge	Learning	Teaching	
EF	.085	.001	.056	
Verbal Skill	.168	073	191*	

Table 2. Correlations with measures, learning, and self-assessment for each robot condition

2a. CORRECT ROBOT					2b. LOGICAL ROBOT			2c. ILLOGICAL ROBOT			
Measure	Classification Task Knowledge	Learning	Teachin	g Measure	Classification Task Knowledge	Learninç	Teachin	g Measure	Classification Task Knowledge	Learning	Teaching
EF	.124	.075	089	EF	.139	.109	.328*	EF	100	144	081
Verbal Skill	.270	030	.053	Verbal Skill	.192	.119	387*	Verbal Skill	002	245	259

Notes * Correlation is significant at the 0.05 level (2-tailed) Hiaher EF = more executive dysfunction

DISCUSSION

- Children's learning was highest when teaching a robot who made illogical errors (Fig 1).
 - There may be more active engagement (and thus learning) when working with a robot whose responses do not follow a predictable learning pattern.
- Executive functioning and verbal skills were not related to children's learning of the classification system (**Table 1**).
 - Awaiting current behavioural coding of teaching strategies to determine whether these skills related to teaching behaviours.
- Better EF and verbal skills were associated with lower rating in self-assessment for teaching,
- particularly for children teaching the logical robot (Table 2b).
- As the learning pattern of the logical robot was more predictable, children with better cognitive skills may have (accurately) detected that their teaching strategies had no impact on the robot's success.
- This work highlights the importance of examining outcomes in terms of both children's learning and self-reflection (in this learning-by-teaching-a-robot context), as well as the differing roles that robot behaviour and children's cognitive skills play for both outcomes.



Cognitive