1 Preliminaries

1.1 Recall Some Important Notions and Results from Real Analysis

This section is based on *Real Analysis and Applications: Theory in Practice* by Davidson and Donsig (a textbook for AMATH/PMATH 331). The electronic version of the book can be downloaded from the UW Library.

Definition 1. A sequence of real number $\{x_n\}$ is said to converge to $x \in \mathbb{R}$ if for every $\varepsilon > 0$, there exists an integer N_{ε} such that $|x_n - x| < \varepsilon$ for all $n > N_{\varepsilon}$.

Note: Conversely, a sequence of real number $\{x_n\}$ is said to not converge to $x \in \mathbb{R}$ if there exists an $\varepsilon > 0$ such that for every N, there exists an n > N such that $|x_n - x| \ge \varepsilon$.

Definition 2. A sequence of real number $\{x_n\}$ is called a Cauchy sequence if for every $\varepsilon > 0$, there exists an N_{ε} such that $|x_n - x_m| < \varepsilon$ for all $n, m > N_{\varepsilon}$.

Theorem 1 (Bolzano-Weierstrass Theorem). Every bounded sequence of real numbers has a convergent subsequence.

Theorem 2 (Completeness of \mathbb{R}). Let $\{x_n\}$ be a sequence of real number. Then $\{x_n\}$ converges if and only if $\{x_n\}$ is a Cauchy sequence.

Definition 3. A set $S \subset \mathbb{R}$ is said to be bounded above by b if $x \leq b$ for all $x \in S$. A set $S \subset \mathbb{R}$ is said to be bounded below by a if $x \geq a$ for all $x \in S$.

Theorem 3 (Theorem and Definition). A set $S \subset \mathbb{R}$ which is bounded above has a least upper bound or supremum, written

$$M = \sup_{x \in S} x,$$

with the properties

- 1. If $x \in S$, then $x \leq M$.
- 2. If c < M, then there is an $x \in S$ such that x > c.

Example 1. Consider a real-valued $f: S \to \mathbb{R}$ and assume f has a supremum in S, $M = \sup_{x \in S} f(x)$. By definition of the supremum, there is a sequence $\{x_n\} \subset S$ such that $f(x_n) > M - \frac{1}{n}$.

Theorem 4 (Theorem and Definition). A set $S \subset \mathbb{R}$ which is bounded below has a greatest lower bound or infimum, written

$$m = \inf_{x \in S} x,$$

with the properties

1. If $x \in S$, then $x \ge m$.

2. If c > m, then there is an $x \in S$ such that x < c.

Note: For a set S, $\max_{x \in S} x$ and $\sup_{x \in S} x$ are not the same. There are sets where the supremum exists but the maximum does not. For example, S = (0, 1).

Definition 4 (Continuous Functions, $\varepsilon - \delta$ Definition). A function $f : \mathbb{R} \supset \Omega \rightarrow \mathbb{R}$ is continuous at a point $x_0 \in \Omega$ (this automatically means that $f(x_0)$ exists) iff for every $\varepsilon > 0$ there exists a $\delta > 0$ such that

$$|f(x_0) - f(x)| < \varepsilon$$
 whenever $|x_0 - x| < \delta$, $x \in \Omega$.

The function $f : \mathbb{R} \supset \Omega \rightarrow \mathbb{R}$ is said to be continuous on Ω iff f is continuous at every point of Ω .

Definition 5 (Sequential Continuity). A function $f : \mathbb{R} \supset \Omega \rightarrow \mathbb{R}$ is said to be sequentially continuous at a point $x_0 \in \Omega$ iff for every sequence $\{x_n\} \subset \Omega$ converging to x_0 , the sequence $\{f(x_n)\}$ converges to $f(x_0)$.

Proposition 1. A function $f : \mathbb{R} \supset \Omega \rightarrow \mathbb{R}$ is continuous at a point $x_0 \in \Omega$ iff it is sequentially continuous at x_0 .

Proposition 2. A real-valued function that is continuous on a closed and bounded region $\Omega \subset \mathbb{R}$ is bounded, and achieves its supremum and infimum in Ω .

Example 2. Let $f : [a, b] \to \mathbb{R}$ be a continuous function. Since [a, b] is closed and bounded, f is bounded and achieves its supremum and infimum in [a, b]. That is there exist $x_1, x_2 \in [a, b]$ such that

$$f(x_1) = \max_{x \in [a,b]} f(x), \quad f(x_2) = \min_{x \in [a,b]} f(x).$$

Definition 6. Let $\{f_n(x)\}_{n=1}^{\infty}$ be a sequence of real-valued functions on $\Omega \subset \mathbb{R}$. We say that $\{f_n\}$ converges pointwise to a function $f : \Omega \to \mathbb{R}$ if

$$\lim_{n \to \infty} f_n(x) = f(x), \quad \text{for all } x \in \Omega.$$

That is, for each $x \in \Omega$ and for every $\varepsilon > 0$, there exists $N_{\varepsilon,x}$ (depending on ε and x) such that

$$|f_n(x) - f(x)| < \varepsilon$$
 whenever $n > N_{\varepsilon,x}$.

Note:

- Pointwise limit of continuous functions can be discontinuous.
- Limit of integral may not be integral of limit.
- Pointwise limit of discontinuous functions can be continuous.

Definition 7. Let $\{f_n(x)\}_{n=1}^{\infty}$ be a sequence of real-valued functions on $\Omega \subset \mathbb{R}$. We say that $\{f_n\}$ converges uniformly to a function $f: \Omega \to \mathbb{R}$ if given $\varepsilon > 0$, there exists an integer N_{ε} (depending on ε) so that

 $|f_n(x) - f(x)| < \varepsilon$ for all $x \in \Omega$ and for all $n > N_{\varepsilon}$.

Note:

- Uniform convergence implies pointwise convergence.
- If $\{f_n\}$ converges pointwise to f, then f is the only potential limit for uniform convergence.
- Let $\{f_n : S \to \mathbb{R}\}$ be a sequence of continuous functions. If $\{f_n\}$ converges uniformly to a function f, then f is continuous.

Lemma 1 (Minkowski's Inequalities). Let $p \in \mathbb{R}$ and $1 \leq p < \infty$.

1. (for finite sum) Let $x_1, \ldots, x_n, y_1, \ldots, y_n \in \mathbb{R}$. Then

$$\left(\sum_{i=1}^{n} |x_i + y_i|^p\right)^{1/p} \le \left(\sum_{i=1}^{n} |x_i|^p\right)^{1/p} + \left(\sum_{i=1}^{n} |y_i|^p\right)^{1/p}$$

2. (for infinite sequence) Consider $\ell_p = \{x = (x_1, x_2, \ldots), x_i \in \mathbb{R}, \sum_{i=1}^{\infty} |x_i|^p < \infty\}$. Let $x, y \in \ell_p$. Then $x + y \in \ell_p$ and

$$\left(\sum_{i=1}^{\infty} |x_i + y_i|^p\right)^{1/p} \le \left(\sum_{i=1}^{\infty} |x_i|^p\right)^{1/p} + \left(\sum_{i=1}^{\infty} |y_i|^p\right)^{1/p}$$

3. (for integrable functions)

$$\left(\int_{a}^{b} |f(t) + g(t)|^{p} dt\right)^{1/p} \leq \left(\int_{a}^{b} |f(t)|^{p} dt\right)^{1/p} + \left(\int_{a}^{b} |g(t)|^{p} dt\right)^{1/p}$$

1.2 Recall Some Important Notions and Results from Linear Algebra

In this section, let $\mathbb{K} = \mathbb{R}$ or $\mathbb{K} = \mathbb{C}$.

Definition 8. A vector space X over \mathbb{K} is a set X together with an addition, u + v, and a scalar multiplication, αu , satisfies the following rules for every $u, v, w \in X$ and $\alpha, \beta \in \mathbb{K}$:

- 1. $u + v \in X$
- 2. (u+v) + w = u + (v+w)
- $3. \ u+v=v+u$
- 4. There is a vector $0 \in X$, called the zero vector, such that u + 0 = 0 + u = u
- 5. For every $u \in X$, there exists $(-u) \in X$ such that u + (-u) = 0
- 6. $\alpha u \in X$
- 7. $\alpha(\beta u) = (\alpha \beta)u$

- 8. $(\alpha + \beta)u = \alpha u + \beta u$
- 9. $\alpha(u+v) = \alpha u + \alpha v$
- 10. 1 u = u

The elements of a vector space X are called vectors.

Example 3. 1. \mathbb{R}^n is a vector space over \mathbb{R} ; \mathbb{C}^n is a vector space over \mathbb{C}

- 2. $X = \{all \ functions \ f : \mathbb{R} \to \mathbb{R}\}$
- 3. $\ell_p = \{\{x_i\} \subset \mathbb{K} \mid \sum_i |x_i|^p < \infty\}, \text{ where } 1 \le p < \infty.$
- 4. $\ell_{\infty} = \{\{x_i\} \subset \mathbb{K} \mid \sup_i |x_i| < \infty, \forall n\}$

Definition 9. Let X be a vector space over \mathbb{K} . If \mathbb{S} is a subset of X and \mathbb{S} is a vector space under the same operations as X, then \mathbb{S} is called a subspace of X.

Lemma 2. (Subspace Test) If S is a nonempty set of X such that $u + v \in S$ and $\alpha u \in S$ for all $u, v \in S$ and $c \in K$ under the operation of X, then S is a subspace of X.

Example 4. Using subspace test, we can verify the following sets are vector spaces over \mathbb{R} .

- 1. $X = P(x) = \{all \ univariate \ polynomials\}$
- 2. $X = P_n(x) = \{all \ univariate \ polynomials \ of \ degree \ at \ most \ n\}$
- 3. $X = C[a, b] = \{all \ continuous \ functions \ on \ [a, b]\}$
- 4. $X = C^{1}[a, b] = \{all \ continuously \ differentiable \ functions \ on \ [a, b]\}$
- 5. $X = C^{\infty}[a, b] = \{all infinitely differentiable functions on [a, b]\}$
- 6. $X = L_p[a, b] = \{all \ Lebesgue \ integrable \ functions \ on \ [a, b]\} = \{f : [a, b] \to \mathbb{R} \mid \int_{a}^{b} |f(x)|^p dx < \infty\}$
- 7. $X = L_{\infty}[a, b] = \{all bounded almost everywhere functions on [a, b]\}$

Definition 10. Let X be a vector space over \mathbb{K} . The vectors $\{u_1, \ldots, u_k\} \subset X$ are called linearly independent if the only solution to $0 = \alpha_1 u_1 + \cdots + \alpha_k u_k$ is the trivial solution $\alpha_1 = \ldots = \alpha_k = 0$.

If the maximal number of linearly independent vectors in X is $n < \infty$, we say X is an n-dimensional vector space and dim X = n. Any set of n linearly independent vectors in X is called a basis for the vector space X.

We write dim $X = \infty$ if for each n = 1, 2, ..., there exist n linearly independent vectors in X. In this case, X is called an infinite dimensional space.

Convention: $\dim\{\vec{0}\} = 0$.

Example 5. dim $\mathbb{R}^n = n$, dim $P_n(x) = n + 1$, dim $C[a, b] = \infty$.

Lemma 3. Let X be an n-dimensional vector space and $\{u_1, \ldots, u_n\}$ be a basis for X. Then every vector $u \in X$ can be uniquely expressed as a linear combination of $\{u_1, \ldots, u_n\}$.

Definition 11 (Quotient Space). Let \mathbb{V} be a vector space and \mathbb{W} be a subspace of \mathbb{V} . Consider the relation \sim on \mathbb{V} :

For
$$x, y \in \mathbb{V}$$
, $x \sim y \Leftrightarrow x - y \in \mathbb{W}$.

It is easy to verify that relation is an equivalent relation (symmetric, reflexivity, and transitivity). Denote

$$[x] = \{ y \in \mathbb{V} \mid x \sim y \}$$

Define the following set

$$\mathbb{V}/\mathbb{W} = \{ [x] \mid x \in \mathbb{V} \},\$$

with the following operators:

$$[x] + [y] := [x + y], \quad \alpha[x] := [\alpha x],$$

for any $x, y \in \mathbb{V}, \alpha \in \mathbb{K}$. Those operators are well-defined and \mathbb{V}/\mathbb{W} is a vector space. Moreover, if $\dim \mathbb{V} < \infty$, $\dim \mathbb{V}/\mathbb{W} = \dim \mathbb{V} - \dim \mathbb{W}$.

Example 6. Let \mathbb{V} be the set of all real-valued integrable functions on [a, b] and $\mathbb{W} = \{f \in \mathbb{V} \mid f = 0a.e.\}$. We can verify that \mathbb{W} is a subspace of \mathbb{V} , hence \mathbb{V}/\mathbb{W} is also a vector space. Indeed, $L_1[a, b] = \mathbb{V}/\mathbb{W}$.

Definition 12. A map $T : \mathbb{V} \to \mathbb{W}$ between two vector spaces over \mathbb{K} is called a linear operator if it preseves the operations of addition of vectors and multiplication by scalars, *i.e.*,

$$T(\alpha u + \beta v) = \alpha T(u) + \beta T(v).$$

Denote $\ker T = \{u \in \mathbb{V} \mid T(u) = 0\}$ Kernel of T, a subspace of \mathbb{V} . Im $T = \{Tu \mid u \in \mathbb{V}\}$ Image (range) of T, a subspace of \mathbb{W} .

Theorem 5. Let $T : \mathbb{V} \to \mathbb{W}$ be a linear operator between two vector spaces \mathbb{V} and \mathbb{W} over \mathbb{K} . Then

- T is one-to-one iff ker $T = \{\vec{0}\}$
- T is onto iff $\operatorname{Im} T = \mathbb{W}$
- If $\dim \mathbb{V} < \infty$, then $\dim \ker(T) + \dim \operatorname{Im}(T) = \dim \mathbb{V}$.

2 Normed Linear Spaces

Below are contents in the next few weeks.

- 2.1 Normed Linear Spaces: Definitions and Examples
- 2.2 Banach Spaces: Definitions and Examples
- 2.3 Open and Closed Sets
- 2.4 Continuity
- 2.5 The Banach Fixed-Point Theorem and the Iteration Method

2.6 Applications to Ordinary Differential Equations

References:

- Sections 1.2, 1.3, 1.4, 1.5, 1.6, 1.8, 1.9 in Applied Functional Analysis: Applications to Mathematical Physics, by E. Zeidler
- Sections 3.1, 2.1, 2.2, 2.4, 2.5, 2.6, 2.7 in Applied Functional Analysis: Course Notes for AM 731, by D. Siegel