



BRINT: A Binary Rotation Invariant And Noise Tolerant Texture Descriptor

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1 Abstract

Goal: Developing a theoretically simple, yet computationally efficient, noise robust, multiresolution descriptor BRINT to gray scale and rotation invariant Texture Classification (TC) based on Local Binary Pattern (LBP).

- Compact, binary descriptor
- No need for texton dictionary learning
- No tuning of parameters to deal with different datasets
- Highly robust to noise
- Invariance to illumination and rotation variations
- Good classification performance

Main components of the proposed approach

- Local Features: Novel binary features BRINT_C, BRINT_S and BRINT_M based on novel average-before-binarization idea and LBP
→ fast to build, complementary information, robust to noise, invariant to illumination and rotation changes
- Global description: Concatenation of multiple bag-of-words histogram feature from the proposed local features and multiresolution analysis
→ compact feature, efficient, training free
- Classifier: Nearest Neighbor Classifier (NNC) → simple

2 Introduction

Advantages of traditional LBP:

- ease of implementation
- no need for pre-training
- invariance to monotonic illumination changes
- low computational complexity

Disadvantages of the traditional LBP_{r,p} (Refer to Table 1):

1. Rapid increase of feature dimensionality with the increase of scale

2. Failing to capture large-scale texture information

3. Sensitive to image rotation

4. Highly sensitive to noise

Weakness of LBP_{r,p}:

- Having shortcomings 1,2,4 listed above
- Performing poorly for rotation invariant TC

Table 1 Number of patterns of different descriptors

Scale	(r, p)	LBP _{r,p}	LBP _{r,p} ^{ri}	LBP _{r,p} ^{riu2}	CLBP_CSM
Scale 1	(1, 8)	256	36	10	200
Scale 2	(2, 16)	65536	4116	18	648
Scale 3	(3, 24)	16777216	699252	26	1352
Scale 4	(4, 32)	2 ³²	huge	34	2312
Scale 5	(5, 40)	2 ⁴⁰	huge	42	3528
Scale 1-5		infeasible	infeasible	106	8040

Weakness of LBP_{r,p}^{riu2}:

- Sensitive to noise
- Unreliability due to using uniform patterns only

Motivations

- Inheriting all advantages of LBP_{r,p}
- Avoiding the disadvantages of LBP_{r,p}^{riu2}
- Conquering the problem of sensitiveness to noise
- Increasing the feature distinctiveness

3 The Proposed Approach

The construction of the proposed BRINT_S descriptor is illustrated in Fig. 1. We transform the neighbor vector $\underline{x}_{r,8q}$ by local averaging along an arc,

$$y_{r,q,i} = \frac{1}{q} \sum_{k=0}^{q-1} x_{r,8q,(q+k)}, \quad i = 0, \dots, 7, \quad (1)$$

as illustrated in Fig. 1, such that the number of neighbors in $\underline{y}_{r,q}$ is always eight.

Given $\underline{y}_{r,q} = [y_{r,q,0}, \dots, y_{r,q,7}]^T$, we can trivially compute a binary pattern with respect to the center pixel:

$$\text{BNT_S}_{r,q} = \sum_{n=0}^7 s(y_{r,q,n} - x_c) 2^n \quad (2)$$

BRINT_S_{r,q} is defined as

$$\text{BRINT_S}_{r,q} = \min\{\text{ROR}(\text{BNT_S}_{r,q}, i) | i = 0, \dots, 7\}, \quad (3)$$

We compute a binary pattern BNT_M (Binary Noise Tolerant Magnitude) based on via

$$\text{BNT_M}_{r,q} = \sum_{n=0}^7 s(z_{r,q,n} - \mu_{r,q}) 2^n, \quad (4)$$

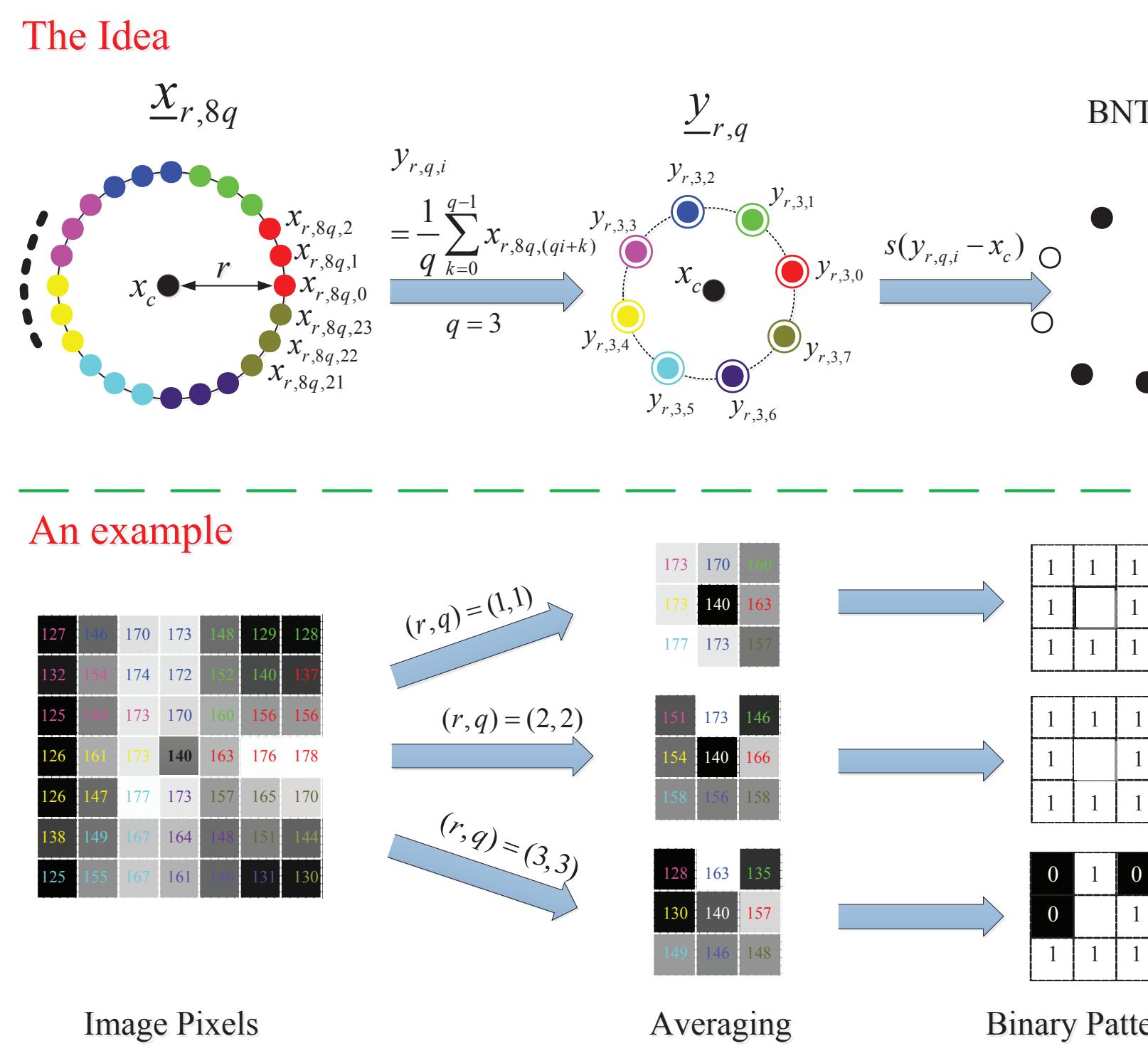


Fig. 1 Illustration of the proposed BNT_S descriptor

where μ_l is the local thresholding value:

$$\mu_{r,q}^l = \frac{1}{8} \sum_{n=0}^7 z_{r,q,n}. \quad (5)$$

With BNT_M defined, BRINT_M is defined as

$$\text{BRINT_M}_{r,q} = \min\{\text{ROR}(\text{BNT_M}_{r,q}, i) | i = 0, \dots, 7\}. \quad (6)$$

Finally, we also represent the center pixel in one of two bins:

$$\text{BRINT_C}_r = s(x_c - \mu_{I,r}) \quad (7)$$

where $\mu_{I,r}$ is the mean of the whole image excluding boundary pixels:

$$\mu_{I,r} = \frac{1}{(M-2r)(N-2r)} \sum_{i=r+1}^{M-r} \sum_{j=r+1}^{N-r} x(i,j). \quad (8)$$

Multiresolution analysis:

We evaluated up to nine scales (Multiple-Scale, MS). At each scale (Single-Scale, SS), we adopt the BRINT_CS_{r,q}-CM_{r,q} descriptor, meaning the joint histogram BRINT_C * BRINT_S_{r,q} concatenated with BRINT_C * BRINT_M_{r,q}.

Classifier: The histogram features are classified according to their normalized histogram feature vectors \mathbf{h}_i and \mathbf{h}_j , using χ^2 distance metric $\chi^2(\mathbf{h}_i, \mathbf{h}_j) = \frac{1}{2} \sum_k \frac{|\mathbf{h}_i(k) - \mathbf{h}_j(k)|^2}{\mathbf{h}_i(k) + \mathbf{h}_j(k)}$. The NNC classifier is used.

4 Results

Table 2 BRINT vs. conventional CLBP at single scales.

Methods	SS1	SS2	SS3	SS4	SS5	SS6	SS7	SS8	SS9
	MS3	MS4	MS5	MS6	MS7	MS8	MS9	Outex_TC10	
BRINT_CS_CM	91.87	96.43	96.04	94.04	95.16	94.51	91.61	92.16	93.78
CLBP_CS ^{ri} _CM ^{ri}	91.87	95.34	89.14	84.95	80.89	78.10	73.83	70.44	67.92
CLBP_CS ^{riu2} _CM ^{riu2}	95.68	98.23	98.72	98.96	98.05	97.58	97.71	96.77	96.30
Outex_TC12.000									
BRINT_CS_CM	86.46	93.38	94.47	91.06	92.15	89.86	89.65	89.38	90.72
CLBP_CS ^{ri} _CM ^{ri}	86.46	92.62	88.56	81.27	79.86	77.62	73.36	69.63	67.94
CLBP_CS ^{riu2} _CM ^{riu2}	89.81	94.31	94.88	93.98	90.56	87.85	88.26	87.71	
Outex_TC12.001									
BRINT_CS_CM	88.50	93.98	94.40	90.81	92.27	90.42	88.80	89.70	90.97
CLBP_CS ^{ri} _CM ^{ri}	88.50	93.01	87.82	81.78	79.26	76.48	73.12	69.21	68.75
CLBP_CS ^{riu2} _CM ^{riu2}	91.44	94.47	93.19	92.41	88.98	85.83	86.90	88.01	86.90

Table 3 BRINT vs. conventional CLBP at multiple scales.

Methods	MS2	MS3	MS4	MS5	MS6	MS7	MS8	MS9	
	Outex_TC10								
BRINT_CS_CM	96.95	98.52	99.04	99.32	99.30	99.40	99.35		
CLBP_CS ^{ri} _CM ^{ri}	96.28	95.21	93.44	91.56	90.60	89.14	88.07	87.58	
CLBP_CS ^{riu2} _CM ^{riu2}	98.41	99.30	99.43	99.45	99.51	99.53	99.48	99.48	
Outex_TC12.000									
BRINT_CS_CM	94.24	96.23	97.04	97.18	97.22	97.43	97.64	97.69	
CLBP_CS ^{ri} _CM ^{ri}	93.17	94.56	93.29	91.25	88.82	87.55	86.92	86.41	
CLBP_CS ^{riu2} _CM ^{riu2}	95.63	96.81	96.67	96.23	95.95	96.00	96.00	95.97	
Outex_TC12.001									
BRINT_CS_CM	94.35	96.34	97.29	97.41	97.85	97.99	98.29	98.56	
CLBP_CS ^{ri} _CM ^{ri}	93.26	93.63	92.04	90.88	89.47	88.43	87.29	86.78	
CLBP_CS ^{riu2} _CM ^{riu2}	88.01	86.90	95.12	95.63	95.35	94.58	94.40	94.19	
	94.21	93.91							