

Helly-type Theorems in Geometry

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Have you ever wondered how
scheduling surveys like
When2Meet work?

Scheduling Example



Each interval represents a participant's single availability.

Finding a time that works for everyone can be tricky, but if every two participants have some overlap, there is surprisingly always a common time for all. **This is explained by an idea in combinatorial geometry called Helly's Theorem.**

Helly's Theorem in \mathbb{R}

Let \mathcal{S} be a collection of **compact and convex sets** in \mathbb{R} . If \mathcal{S} is **2-linked** (i.e., every 2 sets have a common point), then the **intersection of all sets in \mathcal{S} is non-empty**:

$$\bigcap_{S \in \mathcal{S}} S \neq \emptyset$$

This is the one-dimensional version of Helly's theorem.

Helly's Theorem in \mathbb{R}^d

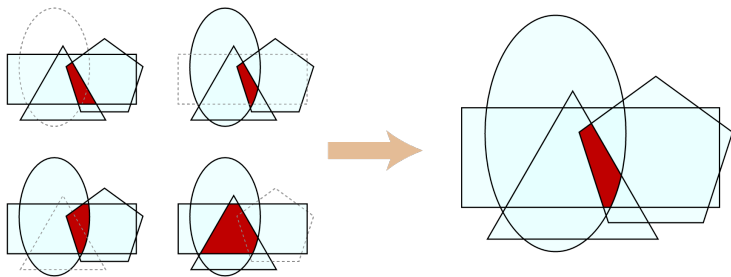
Let \mathcal{C} be a collection of **compact and convex sets** in \mathbb{R}^d . If every $d + 1$ sets in \mathcal{C} have a non-empty intersection, then the intersection of all sets in \mathcal{C} is non-empty:

$$\bigcap_{C \in \mathcal{C}} C \neq \emptyset$$

Helly's Theorem in \mathbb{R}^d

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Classic 2D example: every three shapes intersect, so all shapes share a common point.

Convexity

Definition

A set S is said to be convex if for any two points $x, y \subseteq S$ and any scalar $\lambda \subseteq (0, 1)$, the point $\lambda x + (1 - \lambda)y$ also belongs to S .

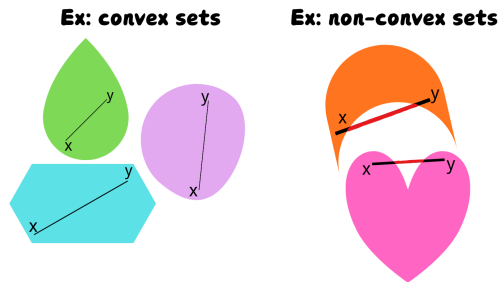


Figure: examples of convex and non-convex sets in R^2

The Role of Compactness

Definition: Compactness in \mathbb{R}^d

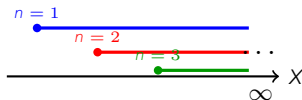
A set $K \subset \mathbb{R}^d$ is **compact** if it is both **closed** and **bounded**.

- **Bounded:** K is contained within a ball of finite radius R ($\exists R > 0$ s.t. $\|x\| \leq R$ for all $x \in K$).
- **Closed:** K contains all its limit points. This means if a sequence $\{x_n\} \subseteq K$ converges to L , then $L \in K$.

Why does it matter for Helly's Theorem?

Consider an **infinite** family of sets $\mathcal{F} = \{F_n\}_{n=1}^{\infty}$ in \mathbb{R}^1 :

$$F_n = [n, \infty) = \{x \in \mathbb{R} \mid x \geq n\}$$

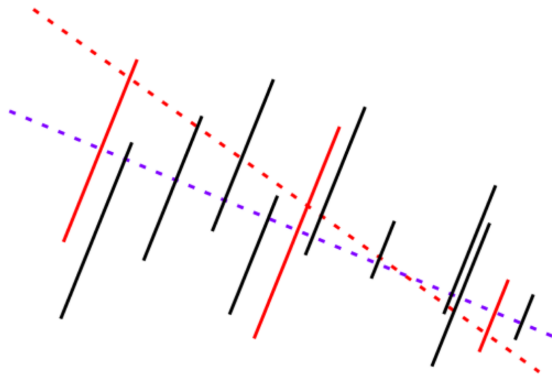




Santaló's Theorem

Santaló's Theorem on Transversals

If every **three** of a family of **parallel** segments (finite or infinite) in the R^2 plane has a **transversal** (a line that passes through them), then all segments have a common transversal.



Red: a transversal for any three segments
Purple: the common transversal for all segments

Proof: Santalós Theorem on Transversals

If every **three** of a family of **parallel** segments in the R^2 plane has a **transversal** (a line that passes through them), then all segments have a common transversal.

- Arrange the segments so that they are vertical on the (x, y) -plane with different x -coordinates.
- Each segment have coordinate $\theta = (x_0, y) : y_0 \leq y \leq y_1$. A **transversal** $y = ax + b$ intersects θ if:

$$y_0 \leq ax_0 + b \leq y_1$$

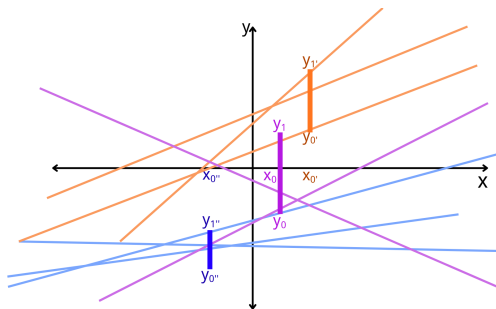


Figure 1: Three (x, y) plane segments with sample transversals.

Proof: Santalós Theorem on Transversals

- Every transversal for a segment form a strip in the (a, b) plane bounded by the lines:

$$\mathbf{b} = -\mathbf{x}_0\mathbf{a} + \mathbf{y}_0$$

$$\mathbf{b} = -\mathbf{x}_0\mathbf{a} + \mathbf{y}_1 \quad (\text{note: } x_0, y_0 \text{ and } y_1 \text{ become coefficients})$$

- The different segments correspond to different x_0 thus different slopes, which every two strips must intersect and form a compact shape.

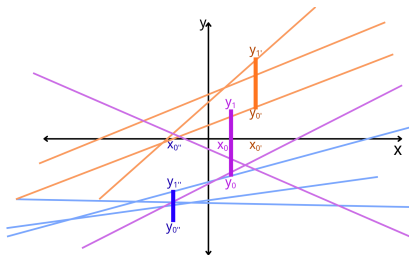


Figure 1: Three (x, y) plane segments with sample transversals.

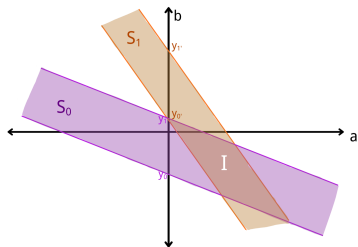


Figure 2: Two transversals from Figure 1 mapped to the (a, b) plane

- In the (a,b) plane, we have a number of convex strips with convex intersections.
- Let $\{S_0, S_1, \dots, S_n\}$ be our full collection of strips. Since they have different slopes, **the intersection of any two sets, I** , must be a non-empty convex set.
- For any other strip S_j not in the previous intersection, consider $K_j = I \cap S_j$. **Since I and S_j are convex, K_j is convex and $K_j \leq I$.**

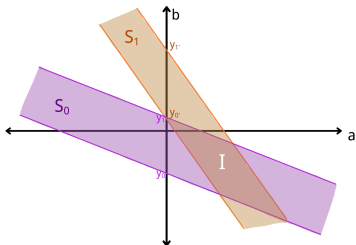


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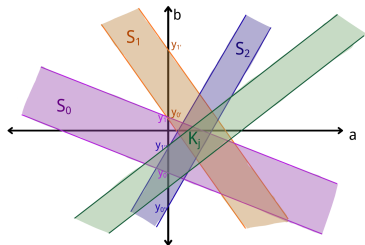


Figure 3

- **Applying Helly's Theorem in R^2 :** By hypothesis, any sub-collection of size 3 has a non-empty intersection. Therefore, the collection of all sets has non-empty intersection.

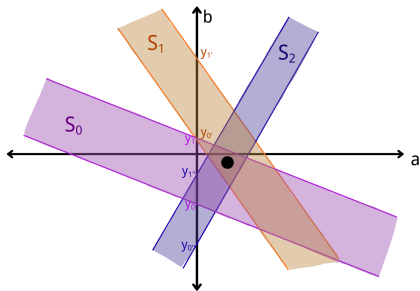


Figure 4: Helly's theorem hypothesis

- **Conclusion:** the collective intersection being non-zero in the (a-b) plane implies at least a common transversal through all segments in the (x-y) plane.

Colorful Helly's Theorem

Colorful Helly's Theorem

Theorem (Colorful Helly). Let $\mathcal{C}_1, \dots, \mathcal{C}_{d+1}$ be finite families of **convex sets** in \mathbb{R}^d (each thought of as a different color).

If for every **colorful selection**

$$C_1 \in \mathcal{C}_1, \dots, C_{d+1} \in \mathcal{C}_{d+1},$$

the intersection

$$\bigcap_{i=1}^{d+1} C_i \neq \emptyset,$$

then there exists an index $j \in \{1, \dots, d+1\}$ such that

$$\bigcap_{C \in \mathcal{C}_j} C \neq \emptyset.$$

Interpretation: if every “rainbow choice” intersects, then one color class intersects entirely.

Lemma (Matoušek, 2002)

Lemma Let \mathcal{C} be a finite family of **compact, convex sets** in \mathbb{R}^d with

$$\bigcap_{C \in \mathcal{C}} C \neq \emptyset.$$

Then there exists a subfamily $\mathcal{C}' \subseteq \mathcal{C}$ of size at most d such that

$$\text{lexmin} \left(\bigcap_{C \in \mathcal{C}'} C \right) = \text{lexmin} \left(\bigcap_{C \in \mathcal{C}} C \right)$$

Remark. We use the *lexicographic order* on \mathbb{R}^d : $x <_{\text{lex}} y$ if at the first coordinate where they differ, $x_j < y_j$. This ordering lets us define a unique “smallest” point in any compact set, denoted $\text{lexmin}(C)$.

Proof Idea of Colorful Helly's Theorem

- Among all *colorful intersections* $C_1 \in \mathcal{C}_1, \dots, C_{d+1} \in \mathcal{C}_{d+1}$, choose sets C_1^*, \dots, C_{d+1}^* that maximize the lexicographic minimum:

$$x^* = \text{lexmin} \left(\bigcap_{i=1}^{d+1} C_i^* \right)$$

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- By Lemma:

$$\text{lexmin} \left(\bigcap_{i=1}^{d+1} C_i^* \right) = \text{lexmin} \left(\bigcap_{i=1}^d C_i^* \right) = x^*$$

Only d sets are needed to determine the lexicographically smallest point of the intersection - so removing one doesn't change it.

Proof Idea of Colorful Helly's Theorem

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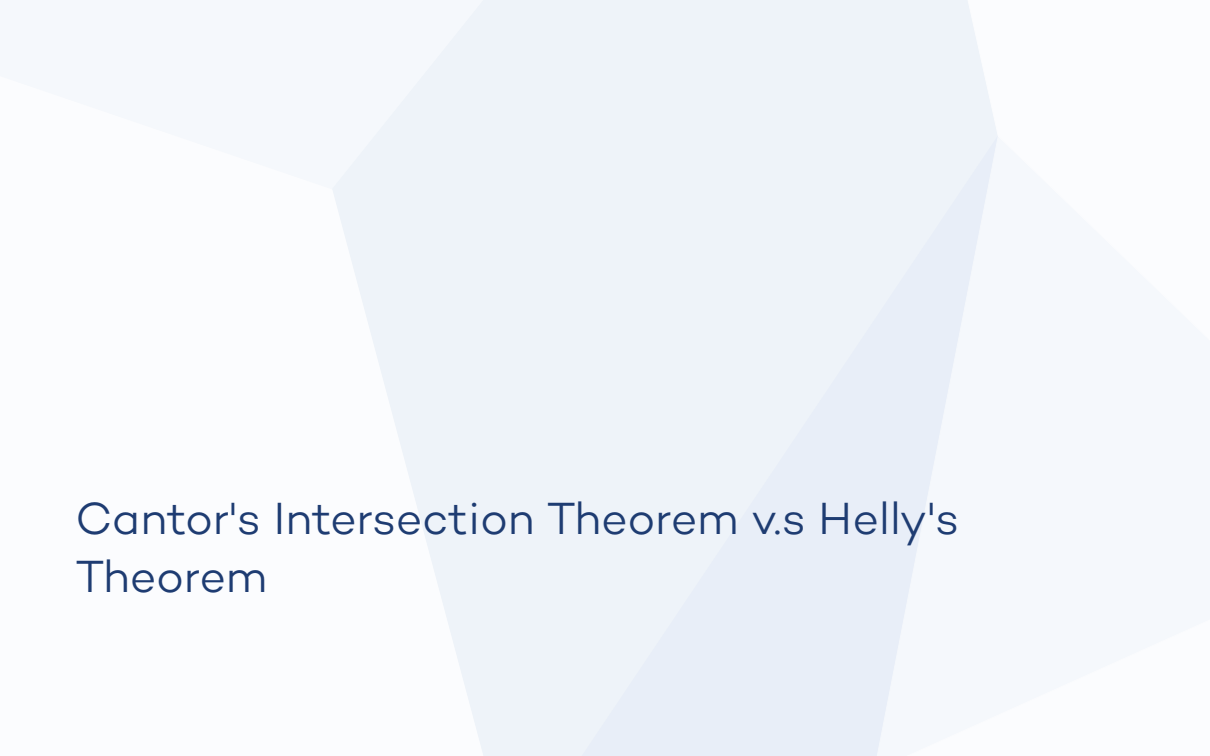
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- Key claim: $x^* \in \bigcap_{C \in \mathcal{C}_{d+1}} C$.
- Reason: adding one more set cannot decrease the lexicographic minimum.
- Therefore, one color class intersects, proving the theorem.

Remark: If all color classes are identical, this reduces to the classical Helly Theorem.



Cantor's Intersection Theorem v.s Helly's Theorem

Cantor's Intersection Theorem

Theorem (Compactness-based)

Let $\{C_k\}$ be a sequence of **non-empty, compact** subsets of \mathbb{R}^d . If they are **nested** ($C_1 \supseteq C_2 \supseteq \dots$), then:

$$\bigcap_{k=1}^{\infty} C_k \neq \emptyset$$

Key Requirements:

- **Compactness:** Sets must be closed and bounded (prevents "escaping" to infinity or holes).
- **Nesting:** Each set must be contained in the previous one.
- *Dimension Independent:* Works in any complete metric space.

Visualizing Cantor's Intersection Theorem

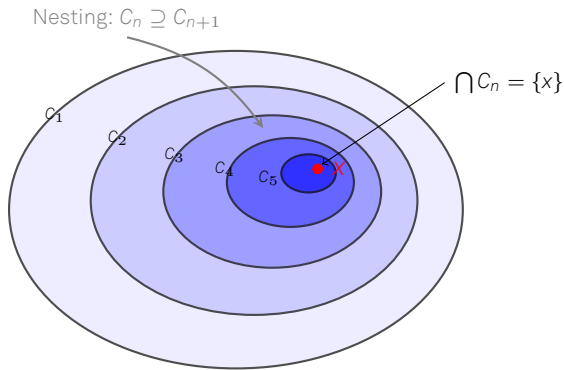
Theorem Statement

Let $\{C_n\}_{n=1}^{\infty}$ be a sequence of non-empty, compact, nested sets in \mathbb{R}^d :

$$C_1 \supseteq C_2 \supseteq C_3 \supseteq \dots$$

Then their intersection is non-empty:

$$\bigcap_{n=1}^{\infty} C_n \neq \emptyset$$



Note: If diameters $\rightarrow 0$, the intersection is a single point.

Think About It

Both theorems guaranty a non-empty intersection, but...
Why can't we simply prove one from the other?

To demonstrate why Helly and Cantor cannot prove each other, we must identify a scenario where one holds true, yet the other one false could be both prerequisites are absent or its logical false

The Missing Bridge: Convex Hulls

Taking the **Convex Hull** ($\text{conv}(C)$) doesn't bridge the gap:

$$\bigcap \text{conv}(C_i) \neq \emptyset \not\Rightarrow \bigcap C_i \neq \emptyset$$

The intersection of convex hulls **does not** guarantee the intersection of the original sets.

Next, let's look at the counter-examples to see why...

Why Helly Cannot Prove Cantor

The Fundamental Limitation of Helly's Theorem: Helly's Theorem is a *geometric* result that relies strictly on **Convexity**. Cantor's Theorem is a *topological* result that does not.

Helly's "Weakness"

If the sets are **not convex**, Helly fails. Even if every pair or triple intersects, the total intersection can be empty.

Cantor's "Strength"

The cantor works for **any** nested compact set (rings, stars, or discrete points), regardless of their shape.

Let's look at a example which use that Helly's "Weakness" and Cantor's "Strength"

Example: Why Helly Cannot Prove Cantor

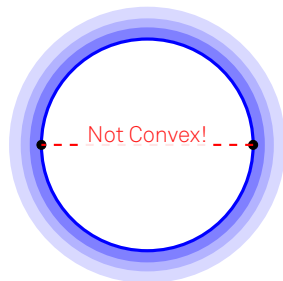
Non-Convex Nested Sets: Why Shape Matters

Cantor: Success ✓

- **Nested:** $C_1 \supset C_2 \supset C_3 \dots$
- **Compact:** Closed and bounded.
- **Limit:** $\bigcap C_n = \text{Unit Circle} \neq \emptyset$.

Helly: Failure ✗

- **Non-Convex:** A ring has a hole shows that it's not convex
- **Result:** Convexity test fails because the center is "missing".



$C_n \rightarrow \text{Unit Circle}$

Why Cantor Cannot Prove Helly

The Fundamental Limitation of Cantor's Theorem: Cantor's is a topological result that relies strictly on **Nesting** ($C_1 \supseteq C_2 \supseteq \dots$). Where Helly's does not.

Cantor's "Weakness"

If the sets are **not nested**, Cantor fails immediately. Even if 1,000 sets pairwise intersect, Cantor provides no guarantee.

Helly's "Strength"

Helly works for **any** finite collection of convex sets, even if they are scattered and **none** are contained within others.

A Counter-Example for Cantor (where Helly still works):

- Consider three **solid disks** D_1, D_2, D_3 in \mathbb{R}^2 arranged like a Clover/Venn diagram.
- Every two disks intersect, and they are all compact.
- **But they are not nested:** $D_1 \not\supseteq D_2 \not\supseteq D_3$.
- *Result:* Cantor's Theorem remains silent, but Helly's Theorem guarantees a triple intersection.

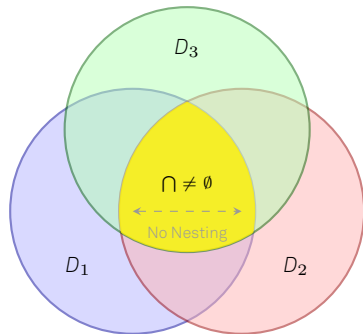
Example: Why Cantor Cannot Prove Helly

Helly: Success ✓

- **Convexity:** Each disk D_i is a solid, convex set.
- **Pairwise:** Every two disks overlap.
- **Result:** Geometry guarantees $\bigcap D_i \neq \emptyset$.

Cantor: Silent ✗

- **Not Nested:** $D_1 \not\supset D_2 \not\supset D_3 \dots$
- **Status:** The "shrinking" machinery is paralyzed.
- **Result:** Cantor provides no information.



Thank You for Listening!

Special thanks: Mathieu Rundström

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Feel free to ask any questions!