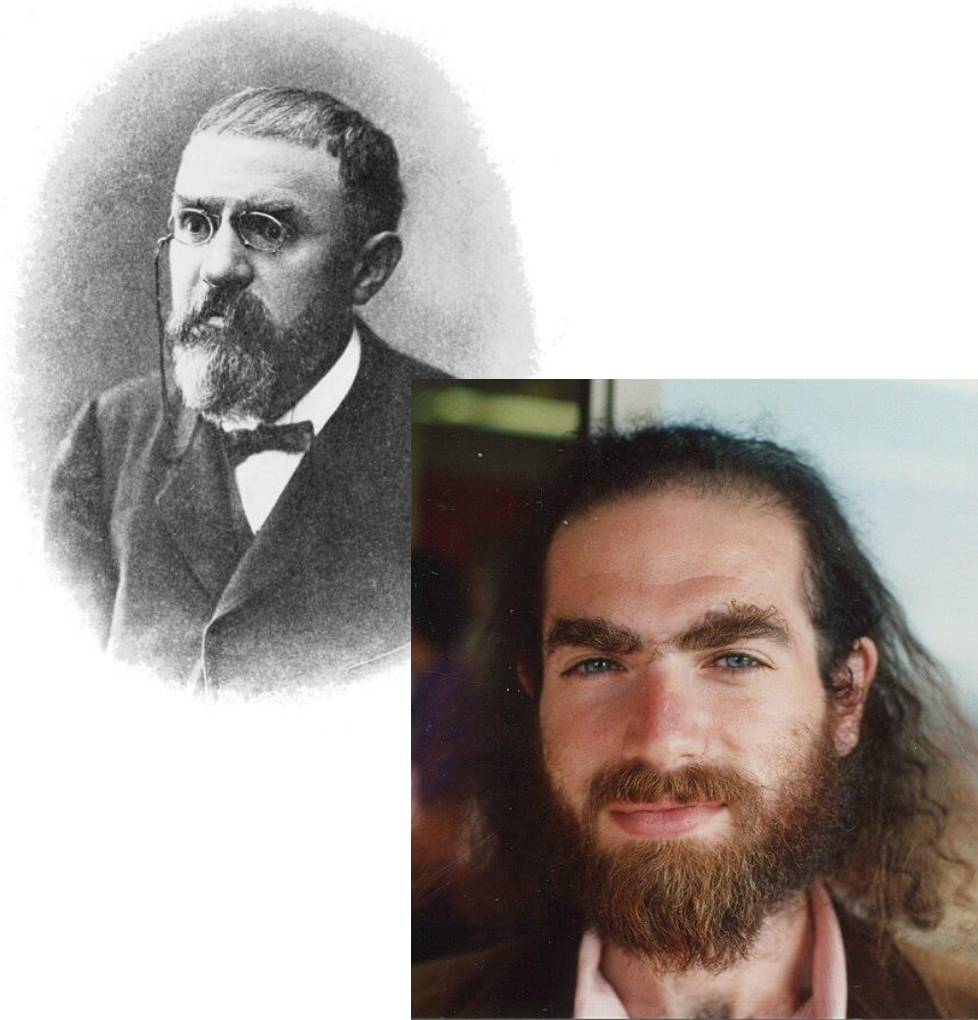


Understanding the Poincaré Conjecture

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Mentees: Paige Schneider, Changhong Li, Kiana Ordoukhani, Siqi Yao

Background of Poincaré Conjecture



- Geometric topology
- Proposed in 1904
- By Henri Poincaré
- The nature of three-dimensional space
- Proof in 2002
- By Grigori Perelman

Fundamental question



If a three-dimensional space has no holes, must it be a three-dimensional sphere?

The formal statement

Poincaré conjecture

*Every three-dimensional **topological manifold** which is **closed, connected**, and has **trivial fundamental group** is **homeomorphic** to the **three-dimensional sphere**.*

Understanding the Poincaré Conjecture

Poincaré conjecture

*Every three-dimensional **topological manifold** which is **closed, connected**, and has **trivial fundamental group** is **homeomorphic** to the **three-dimensional sphere**.*

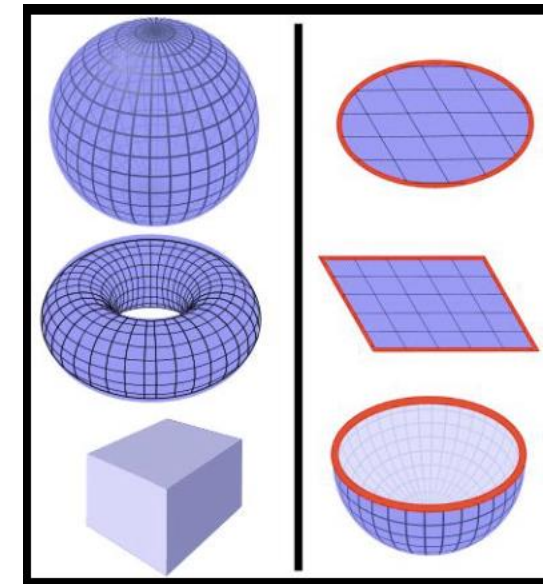
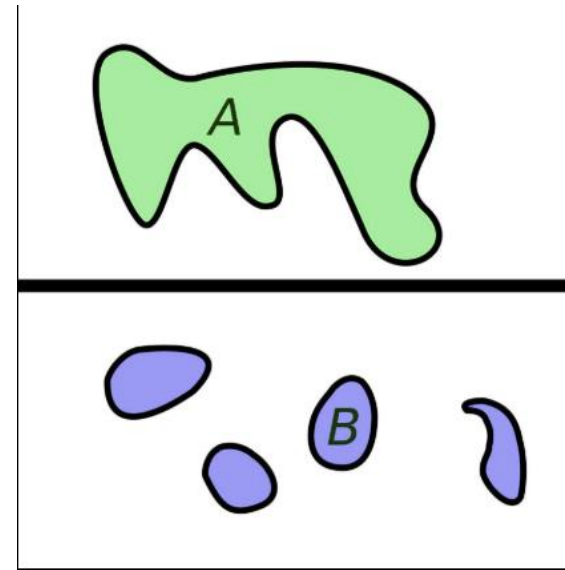
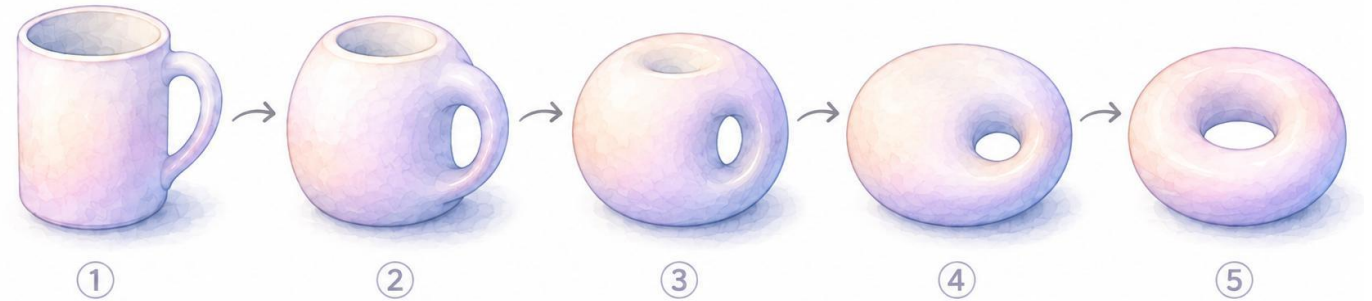
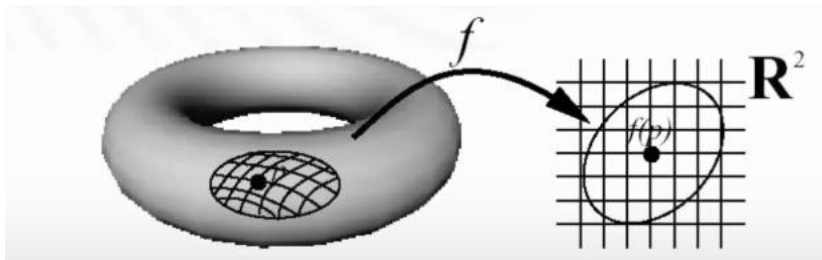
- What is a **topological manifold**? And how it could be **closed and connected**?
- What is the **fundamental group**, and what does "**trivial**" mean?
- What does it mean for two spaces to be **homeomorphic**?
- What is a **3-dimensional sphere**?

Spheres in different dimensions

Dimension	Object	Description
0D	Point	Single dot
1D	Circle (S^1)	All points at distance r from a center in 2D space (circle)
2D	Sphere (S^2)	All points at distance r from a center in 3D space (surface of a ball)
3D	3-Sphere (S^3)	All points at distance r from a center in 4D space

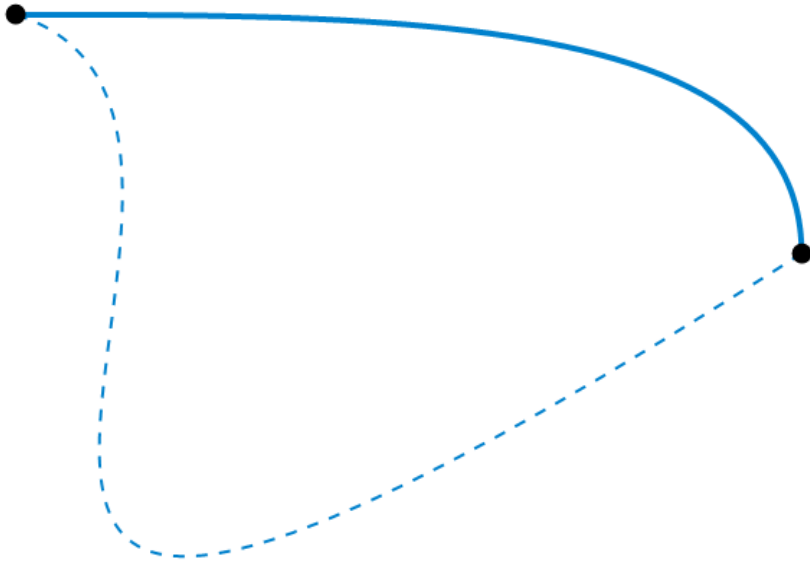
Manifolds

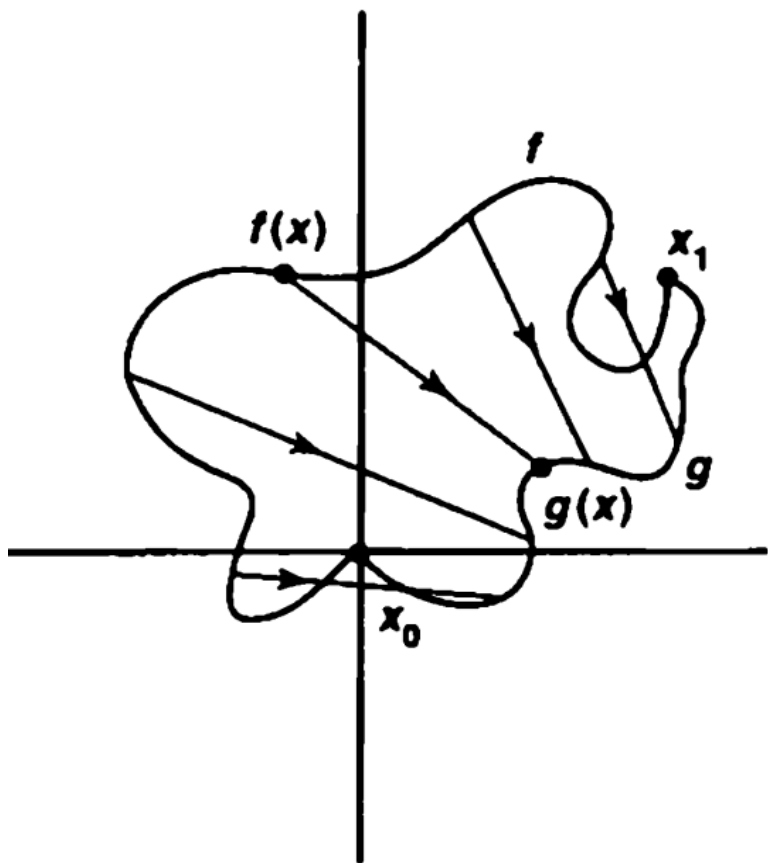
- What Is a Manifold?
- Locally Euclidean
- Local versus Global
- Doughnut and Coffee Cup



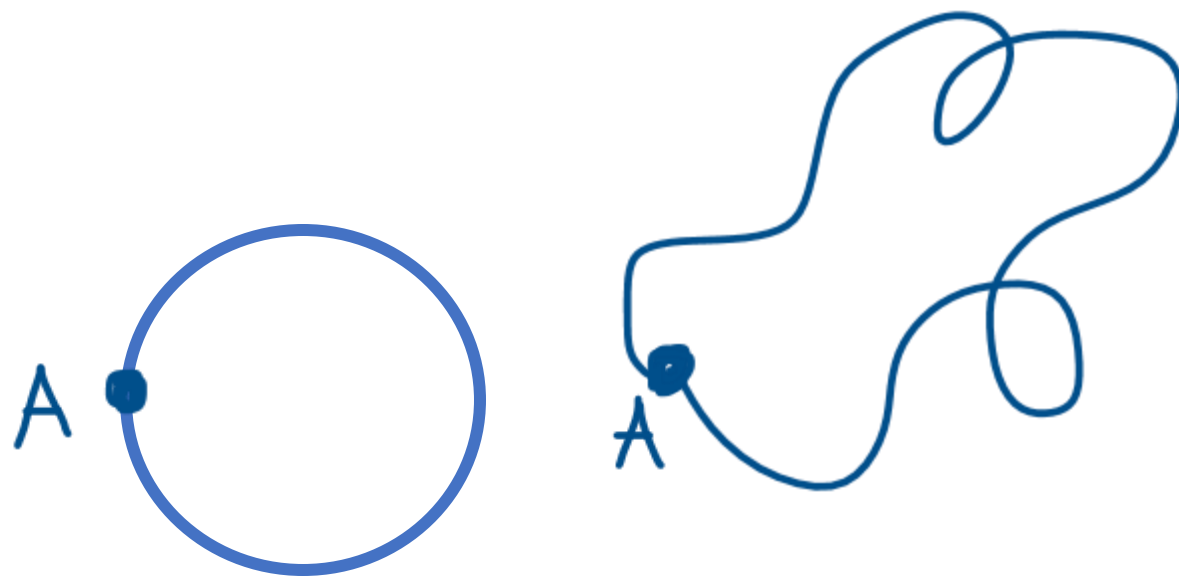
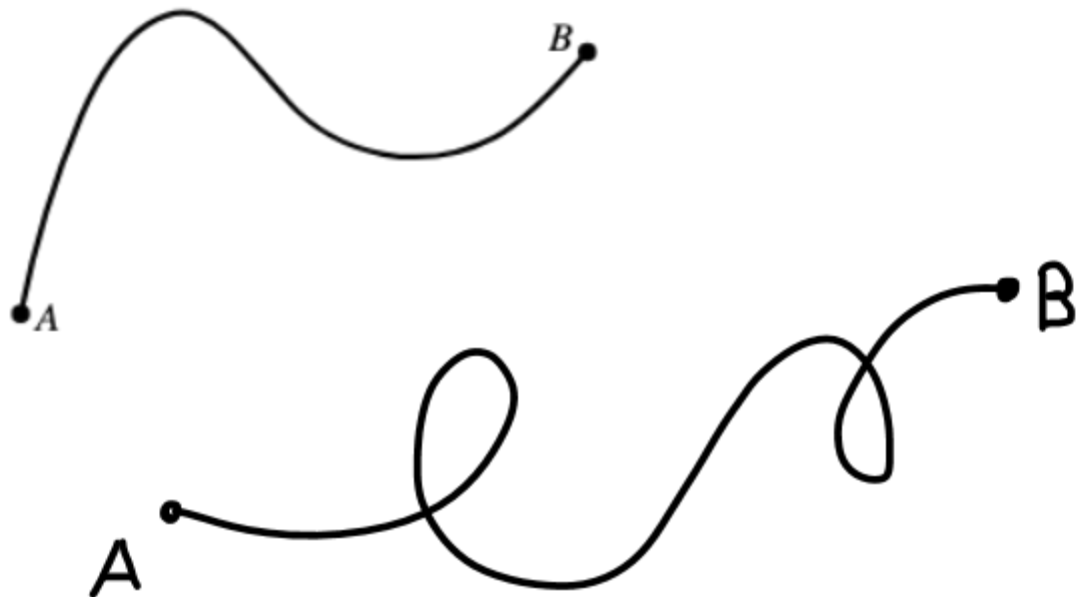
Homotopy Theory

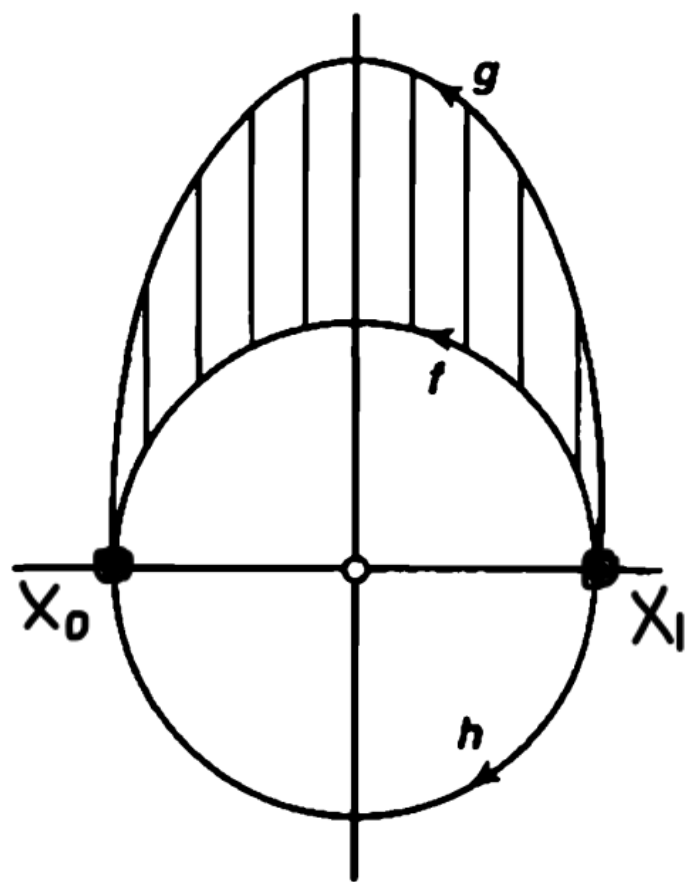
- Two continuous functions from one topological space to another are called homotopic if one can be continuously deformed into the other. This deformation is called a homotopy.



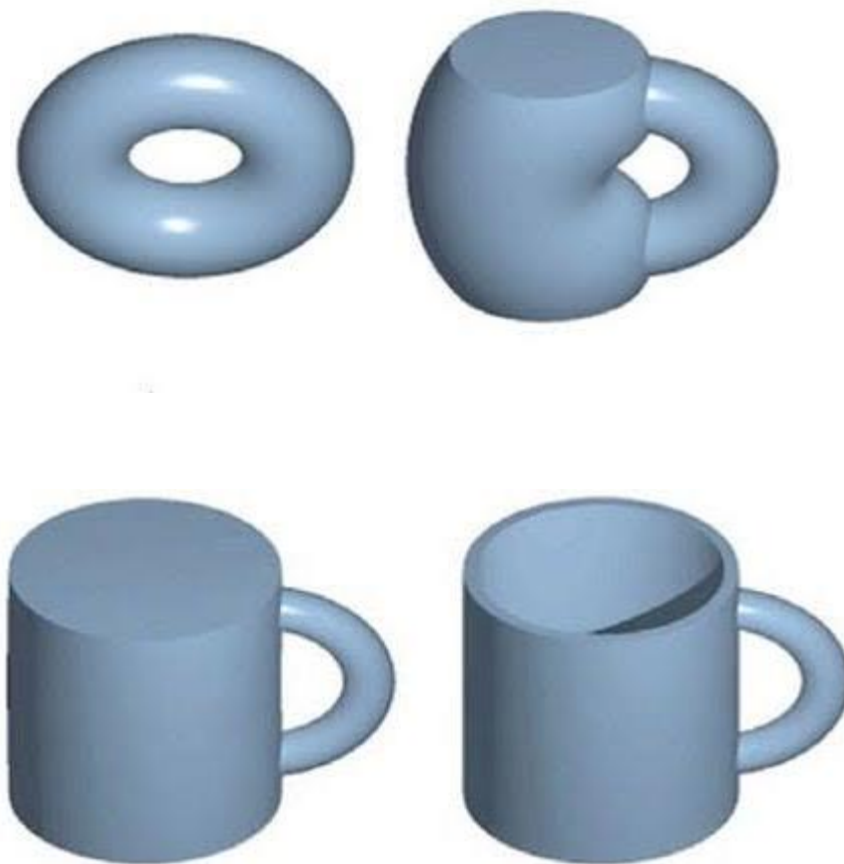


$$F(x, t) = (1 - t)f(x) + tg(x)$$





$$\mathbb{R}^2 \setminus \{0\}$$



Groups

A group is a set G with a binary operation that satisfies:

- Associativity: For all $a, b, c \in G$, $(a \cdot b) \cdot c = a \cdot (b \cdot c)$
- Identity: There exists $e \in G$ such that for all $g \in G$, $g \cdot e = e \cdot g = g$
- Inverse: For every $g \in G$, there exists $h \in G$ such that $g \cdot h = h \cdot g = e$.

Group Presentation

A **group presentation** describes a group by:

- Generators (S): A set of elements that generate the group
- Relations (R): Equations that the generators satisfy

Notation: $\langle S \mid R \rangle$

Example: Cyclic Group $C_n \langle a \mid a^n = 1 \rangle$

Direct Product of groups

Let $(A, \cdot)$ and $(B, \star)$ be groups.

We define the *direct product* of A and B to be the set

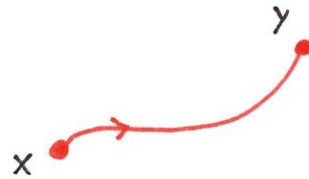
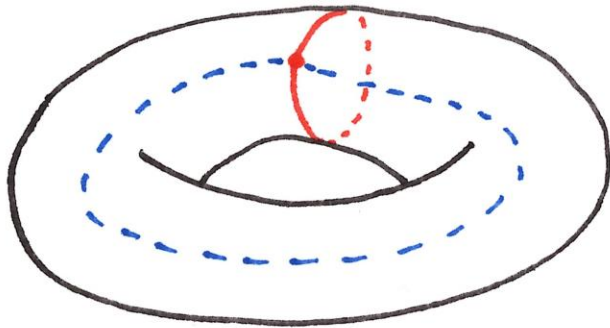
$$A \times B = \{(a, b) : a \in A, b \in B\}$$

equipped with the operation

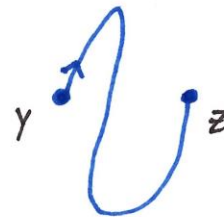
$$(a_1, b_1)(a_2, b_2) = (a_1 \cdot a_2, b_1 \star b_2).$$

Fundamental Groups

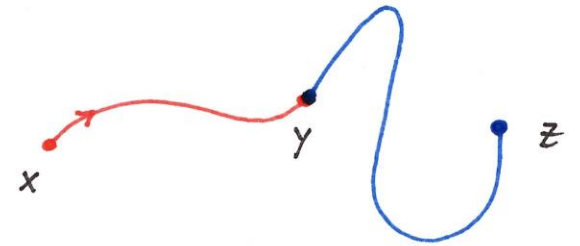
- Elements: Path classes of loops based at a given point
- Operation: Path multiplication



A



B



$A \cdot B$

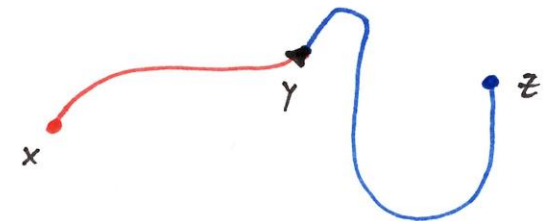
time = 0.5



A



B

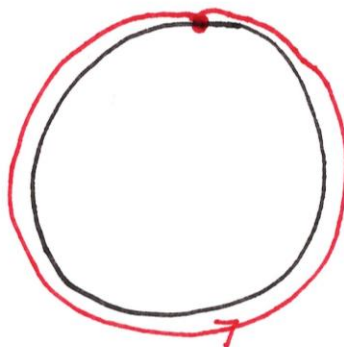


$A \cdot B$

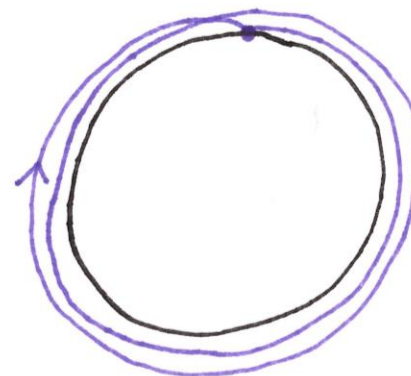
Circle: $\mathbb{Z}$



1

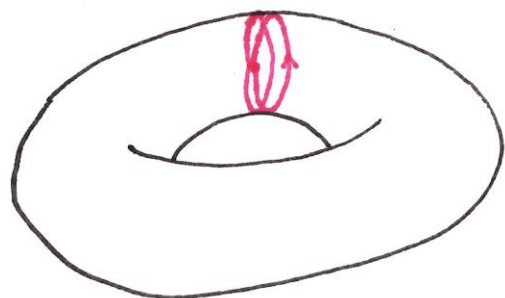
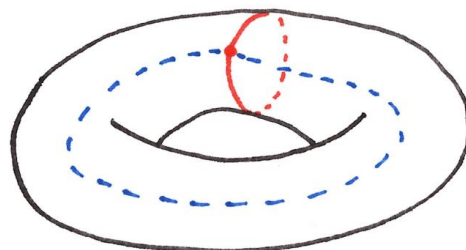


-1

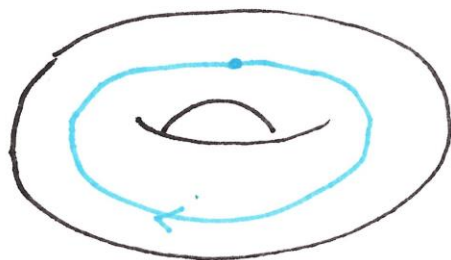


2

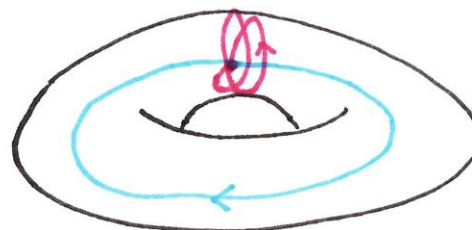
Torus: $\mathbb{Z} \times \mathbb{Z}$



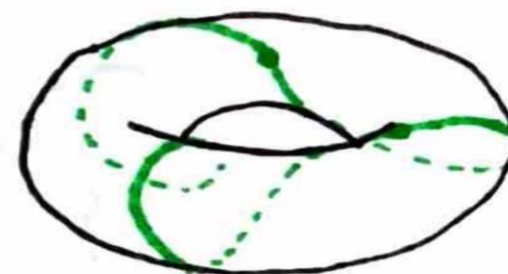
$(-2, 0)$



$(0, 1)$

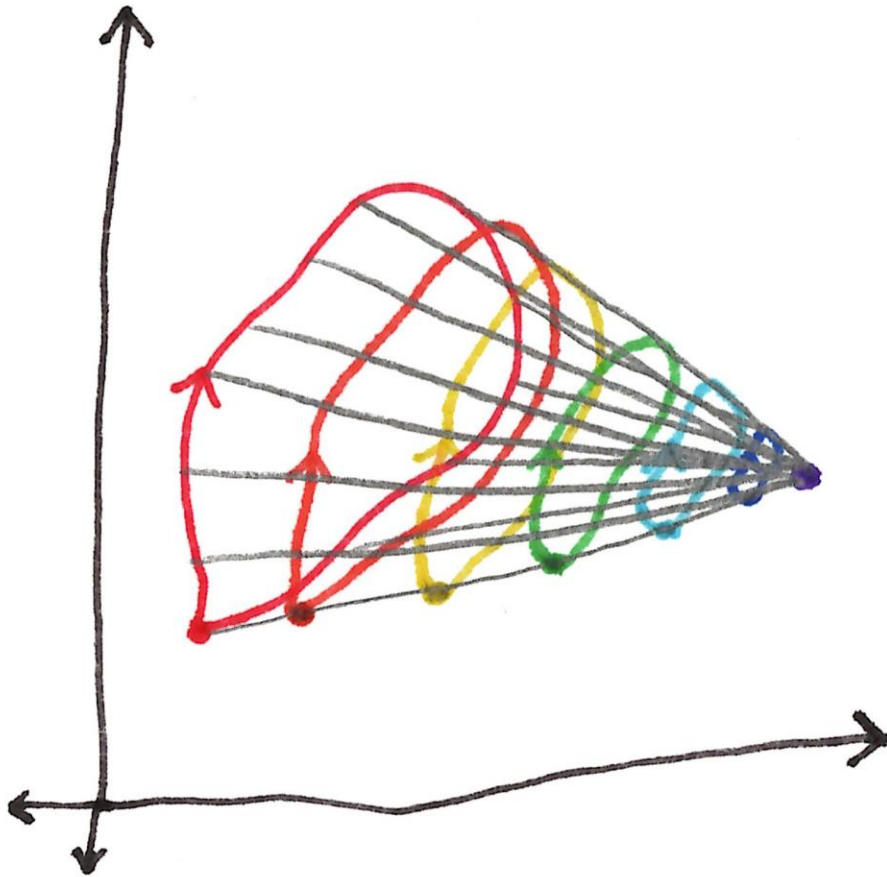


$(-2, 1)$

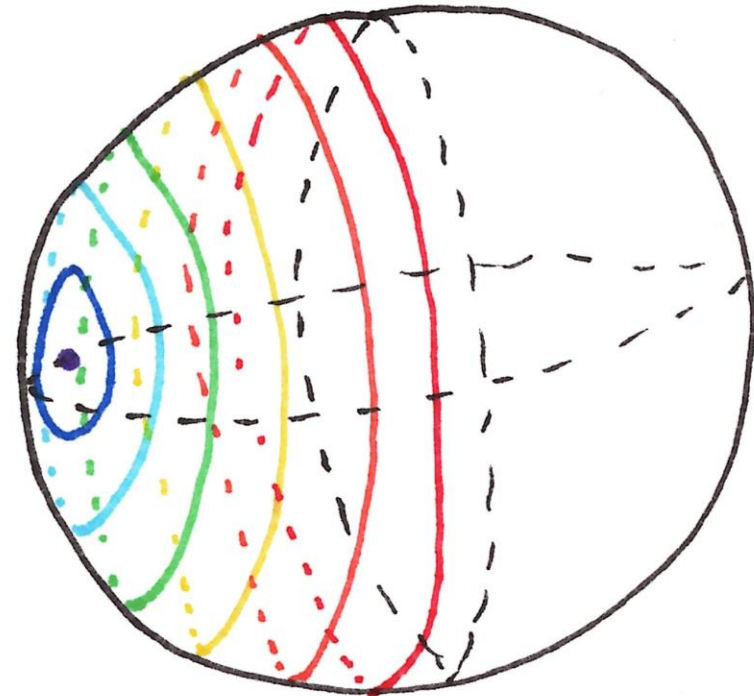


Also $(-2, 1)$

Plane: Trivial group



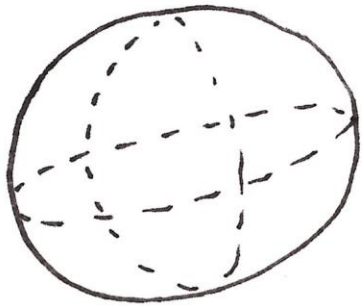
Sphere: Trivial group



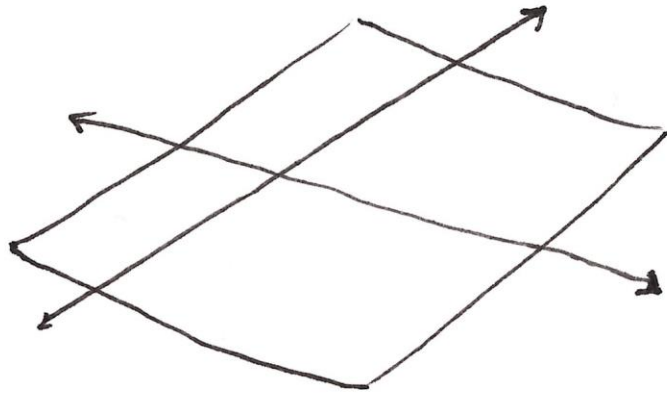
Simply Connected

- Fundamental group is trivial

SIMPLY CONNECTED

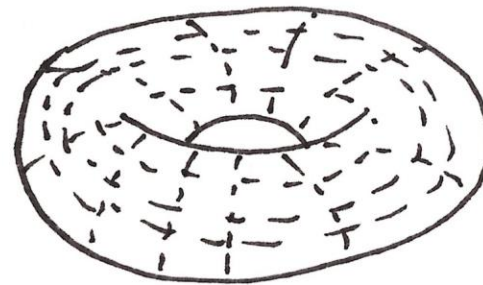


sphere



plane

NOT SIMPLY CONNECTED



torus



circle

Conclusion

- Every 3-dimensional manifold which is closed, connected, and simply connected is homeomorphic to the three-dimensional sphere

