An Introduction to Classical Knot Theory: How to Tell the Difference Between Twisted Piles of String

Isabela Souza Cefrin da Silva, Soumya Menon

Mentor: Robert Harris

University of Waterloo, WiM Directed Reading Program

April 7, 2025

Overview

- Mots
 - What is a Knot?
 - Differentiating Knots
- ② Groups
 - Introduction
 - Wirtinger Presentation
 - The Fundamental Group

What is a Knot?

Simply, it is just a curve that starts and ends in the same location, but can go over or under itself.

Definition (Knot)

A knot K is a simple closed curve in \mathbb{R}^3

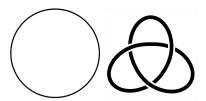


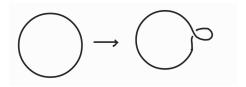
Figure: Unknot (left) and Trefoil Knot (right)

Reidemeister Moves

Intuitively, to show that two knots are different, we need to show that there is no way to transform one knot into the other while keeping its original structure. For this, we need to define what permissable 'moves' we can do to a knot that doesn't change the underlying object.

Reidemeister Moves

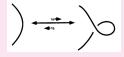
Intuitively, to show that two knots are different, we need to show that there is no way to transform one knot into the other while keeping its original structure. For this, we need to define what permissable 'moves' we can do to a knot that doesn't change the underlying object.



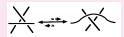
Reidemeister Moves

Definition (Reidemeister Moves)

Operations that can be performed on a knot diagram without altering the corresponding knot.







Why do we need other methods?

Sometimes, it's not easy to keep trying Reidemeister moves until you arrive at a simpler knot...

Why do we need other methods?

Sometimes, it's not easy to keep trying Reidemeister moves until you arrive at a simpler knot...



Why do we need other methods?

Sometimes, it's not easy to keep trying Reidemeister moves until you arrive at a simpler knot...

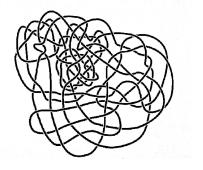


Figure: Haken's Gordian Unknot

Group Definition

Definition (Group)

Let G be a set and * be an operation defined on $G \times G$. We say G = (G, *) is a group if the following are satisfied:

- * is associative: a*(b*c) = (a*b)*c for all $a,b,c \in G$;
- ② There exists an identity element $1 \in G$: a * 1 = 1 * a = a for all $a \in G$;
- **3** Every $a \in G$ has an inverse: for all $a \in G$ there exists $b \in G$ such that a * b = b * a = 1.

Group Definition

Definition (Group)

Let G be a set and * be an operation defined on $G \times G$. We say G = (G, *) is a group if the following are satisfied:

- * is associative: a*(b*c) = (a*b)*c for all $a,b,c \in G$;
- ② There exists an identity element $1 \in G$: a * 1 = 1 * a = a for all $a \in G$;
- **3** Every $a \in G$ has an inverse: for all $a \in G$ there exists $b \in G$ such that a * b = b * a = 1.
 - $\mathbb{Z}, \mathbb{Q}, \mathbb{R}, \mathbb{C}$ are groups with addition.

• Note that by the definition of the group it is not always true that, for all $a, b \in G$:

$$a * b = b * a$$

• Note that by the definition of the group it is not always true that, for all $a, b \in G$:

$$a * b = b * a$$

• If this holds, then the group is called an *abelian group*.

 Note that by the definition of the group it is not always true that, for all a, b ∈ G:

$$a * b = b * a$$

- If this holds, then the group is called an abelian group.
- $\mathbb{Z}, \mathbb{Q}, \mathbb{R}, \mathbb{C}$ are abelian groups with addition.

 Note that by the definition of the group it is not always true that, for all a, b ∈ G:

$$a * b = b * a$$

- If this holds, then the group is called an abelian group.
- $\mathbb{Z}, \mathbb{Q}, \mathbb{R}, \mathbb{C}$ are abelian groups with addition.
- Key observation: If one group is abelian and another isn't, they can't be (structurally) the same!

- What is a Group Presentation $\langle S \mid R \rangle$?
 - *S* is the set of *generators* ("ingredients") that combine to form group elements.
 - *R* is the set of *relations* among these generators.

- What is a Group Presentation $\langle S \mid R \rangle$?
 - *S* is the set of *generators* ("ingredients") that combine to form group elements.
 - *R* is the set of *relations* among these generators.
- Example: $\mathbb{Z}_n = \langle a \mid a^n = 1 \rangle$.

- What is a Group Presentation $\langle S \mid R \rangle$?
 - *S* is the set of *generators* ("ingredients") that combine to form group elements.
 - R is the set of relations among these generators.
- Example: $\mathbb{Z}_n = \langle a \mid a^n = 1 \rangle$.
- Note: There might be more than one group representation for the same group. For example:

$$\textit{G} = \langle \textit{x}, \textit{y} \mid \textit{xyxy}^{-1} \textit{x}^{-1} \textit{y}^{-1} = 1 \rangle \cong \langle \textit{g}, \textit{h} \mid \textit{g}^{-3} \textit{h}^{-2} = 1 \rangle$$

- Pick an orientation.
- 2 Label each "arc".
- Examine each crossing.

Note: Be consistent!

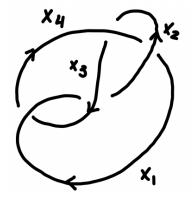
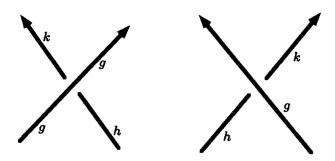


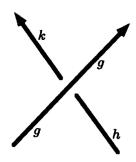
Figure: Figure-eight Knot

• There are two possible cases for each crossing:

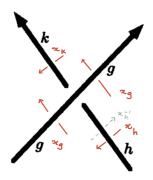


 At the left, we have what we call a right-handed crossing. How do I know that? Right-hand rule!

• In the case of the right-handed crossing, the labels look like:

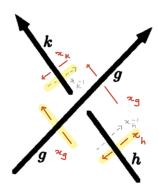


- In the case of the right-handed crossing, the labels look like:
- Add a right-to-left line under each arc, and consider inverses as going the opposite direction

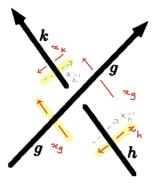


- In the case of the right-handed crossing, the labels look like:
- Add a right-to-left line under each arc, and consider inverses as going the opposite direction
- Create an equation for the relationship between lines:

$$x_g = x_h x_g x_k^{-1}$$

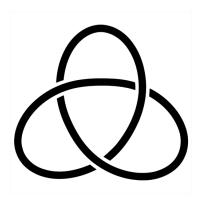


- In the case of the right-handed crossing, the labels look like:
- Add a right-to-left line under each arc, and consider inverses as going the opposite direction
- Create an equation for the relationship between lines:
 - $x_g = x_h x_g x_k^{-1}$
- Repeat for every crossing in the knot!

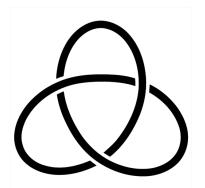


• But how does this work in practice? How can we find a group from the knot diagram?

- But how does this work in practice? How can we find a group from the knot diagram?
- Consider the Trefoil knot:



- But how does this work in practice? How can we find a group from the knot diagram?
- Consider the Trefoil knot:

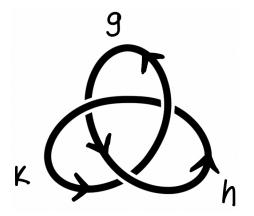


• We start by finding the equations for each crossing.

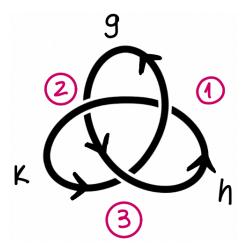
Pick an orientation.



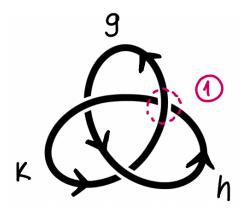
2 Label each "arc".



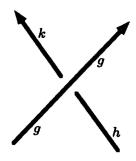
Examine each crossing.



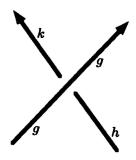
• We'll start with crossing 1:



• It looks like:

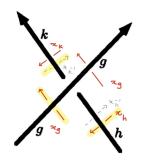


• It looks like:



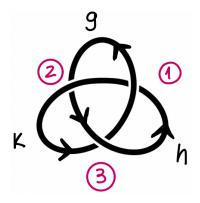
... A right-handed crossing!

We already calculated that before!



- From crossing 1 we get:
 - $\bullet \ \ x_g = x_h x_g x_k^{-1}$
- Equivalent to:
 - $x_k = x_g^{-1} x_h x_g (1)$

- If we repeat this process for the other crossings, it follows that:
 - From crossing 2 we get: $x_k = x_g x_k x_h^{-1} (2)$
 - From crossing 3 we get: $x_h = x_k x_h x_g^{-1} (3)$



• By subbing (1) into (2), we can eliminate x_k :

$$x_g^{-1}x_hx_g=x_k$$

$$x_g^{-1} x_h x_g = x_k$$
$$= x_g x_k x_h^{-1}$$

$$x_g^{-1} x_h x_g = x_k$$

= $x_g x_k x_h^{-1}$
= $x_g (x_g^{-1} x_h x_g) x_h^{-1}$

$$x_g^{-1} x_h x_g = x_k$$

$$= x_g x_k x_h^{-1}$$

$$= x_g (x_g^{-1} x_h x_g) x_h^{-1}$$

$$= x_h x_g x_h^{-1}$$

$$x_g^{-1} x_h x_g = x_k$$

$$= x_g x_k x_h^{-1}$$

$$= x_g (x_g^{-1} x_h x_g) x_h^{-1}$$

$$= x_h x_g x_h^{-1}$$

$$x_g^{-1}x_hx_g = x_k$$

$$= x_gx_hx_h^{-1}$$

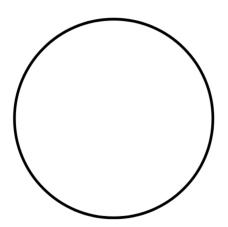
$$= x_g(x_g^{-1}x_hx_g)x_h^{-1}$$

$$= x_hx_gx_h^{-1}$$

- Thus, one group presentation of the trefoil knot is:

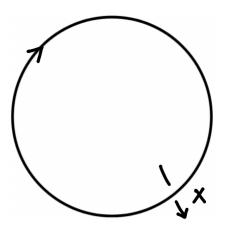
Example: Unknot

• What is the knot group of the unknot?



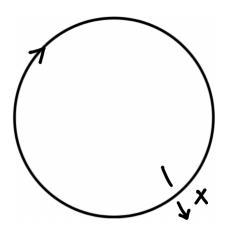
Example: Unknot

• Label arcs... but there are no crossings!



Example: Unknot

• Label arcs... but there are no crossings!



• It is $\langle x \rangle \cong \mathbb{Z}!$

Example: Unknot vs Trefoil Knot

 The group presentation of the trefoil knot group that we found before was

$$\langle x_g, x_h \mid x_g^{-1} x_h x_g = x_h x_g x_h^{-1} \rangle \cong \langle x_g, x_h \mid x_h x_g = x_g x_h x_g x_h^{-1} \rangle$$
 (non-abelian).

Example: Unknot vs Trefoil Knot

 The group presentation of the trefoil knot group that we found before was

$$\langle x_g, x_h \mid x_g^{-1} x_h x_g = x_h x_g x_h^{-1} \rangle \cong \langle x_g, x_h \mid x_h x_g = x_g x_h x_g x_h^{-1} \rangle$$
 (non-abelian).

• Whereas the unknot group is $\langle x \rangle \cong \mathbb{Z}$ (abelian).

Example: Unknot vs Trefoil Knot

 The group presentation of the trefoil knot group that we found before was

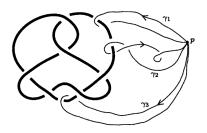
$$\langle x_g, x_h \mid x_g^{-1} x_h x_g = x_h x_g x_h^{-1} \rangle \cong \langle x_g, x_h \mid x_h x_g = x_g x_h x_g x_h^{-1} \rangle$$

- (non-abelian).
- ullet Whereas the unknot group is $\langle x \rangle \cong \mathbb{Z}$ (abelian).
- This means they can not be the same!

The Fundamental Group

Definition (The Fundamental Group)

For a knot K in \mathbb{R}^3 , fix a point p in $(\mathbb{R}^3 - K)$. The **Fundamental Group** of K, $\pi_1(\mathbb{R}^3 - K)$, is the set of equivalence classes of closed oriented paths in $(\mathbb{R}^3 - K)$ that begin and end at p.



And the method of labelling that we showed is the **Wirtinger Presentation**

Limitations

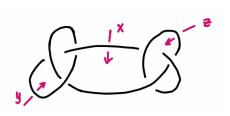
• One knot can have multiple knot group presentations.

Limitations

- One knot can have multiple knot group presentations.
- Different knots can have the same knot group presentation:

Limitations

- One knot can have multiple knot group presentations.
- Different knots can have the same knot group presentation:



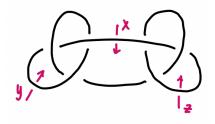


Figure: Granny Knot

Figure: Square Knot

$$\langle x, y, z \mid xyx = yxy, xzx = zxz \rangle$$

We learned...

• What a knot is

We learned...

- What a knot is
- Knot Groups

We learned...

- What a knot is
- Knot Groups
- Using Knot Groups to differentiate knots

We learned...

- What a knot is
- Knot Groups
- Using Knot Groups to differentiate knots

There are also many other methods (knot invariants) that can help us study knots

- Algebraic methods (e.g. Alexander Polynomial)
- Knot Colourings
- and many more!



References

Hannah Keese.

Computing the alexander polynomial from seifert surfaces.

W. B. Raymond Lickorish.

An introduction to knot theory.

Springer International Publishing, 1997.

Charles Livingston.

Knot theory, volume 24.

Mathematical Association of America, 1993.

James Munkres.

Topology.

Pearson Education, 2nd edition, 2013.

Dale Rolfsen.

Knots and links.

American Mathematical Society; Oxford University Press, 2004.

Thank you!